

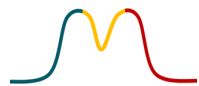
**D INFK**

# Surprising Failures of Standard Practices in ML

When the Sample Size is Small

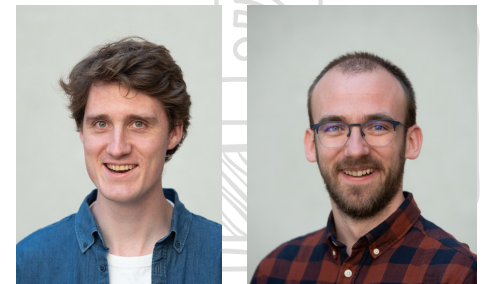
December 3<sup>rd</sup> 2022, ICBINB NeurIPS Workshop

Fanny Yang, joint work with **J. Clarysse, A. Tifrea**



Statistical Machine Learning group, CS department, ETH Zurich

**ETH** zürich

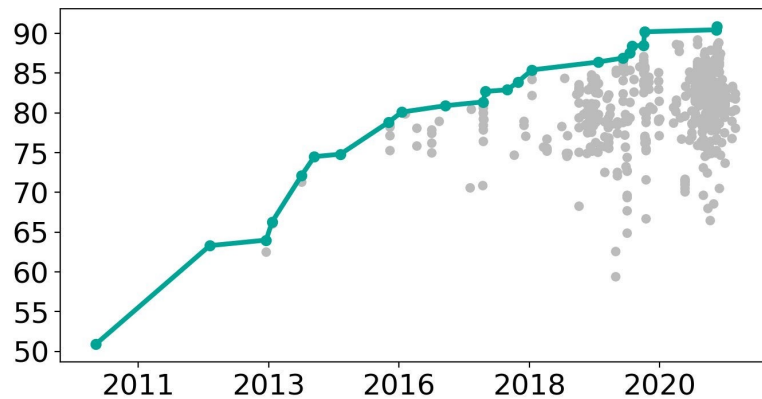


# Reliability crisis in modern supervised learning

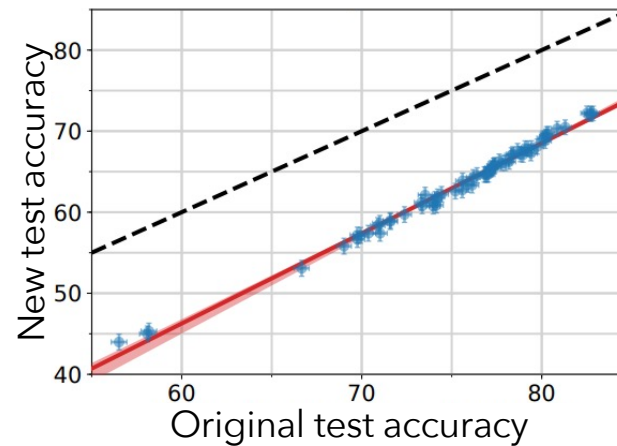
Modern ML works well ...

sometimes maybe not so much...

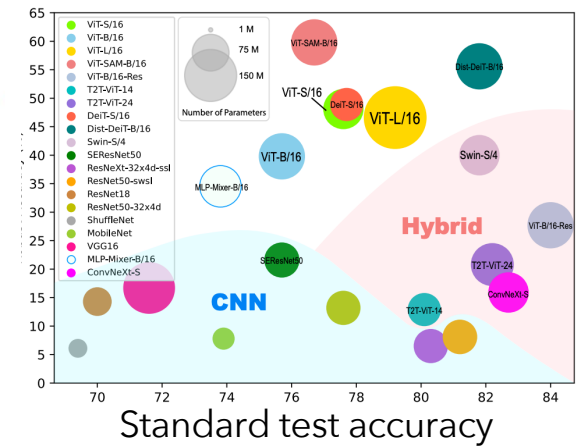
Top1 test accuracy on ImageNet



Top1-accuracy on new ImageNet

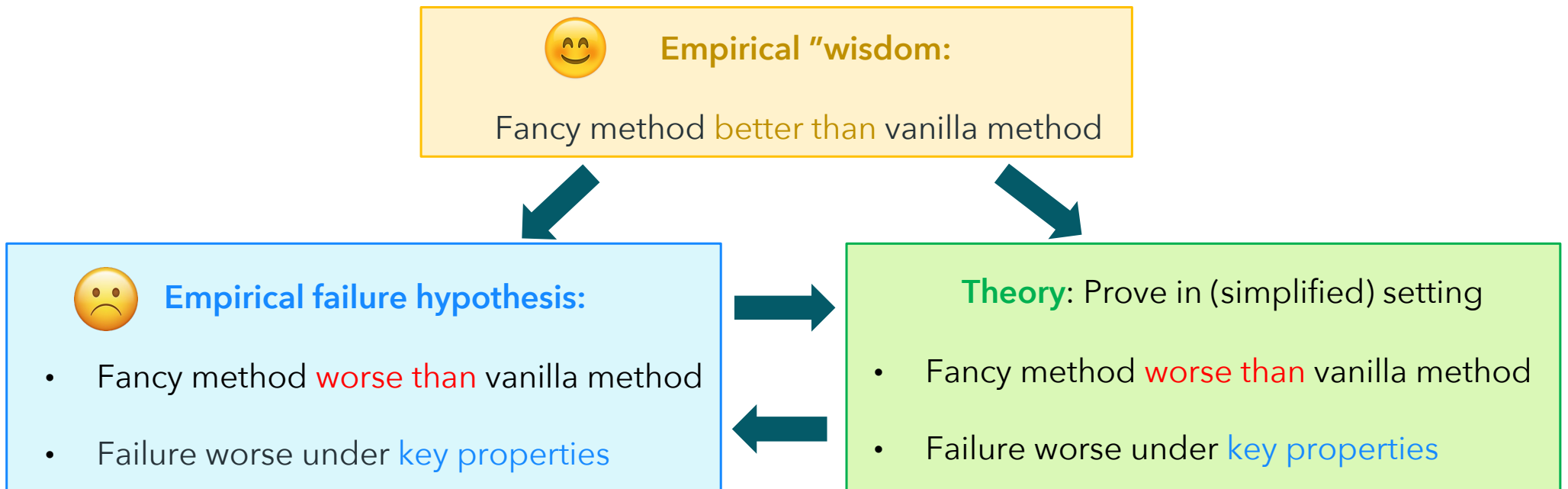


Robust accuracy on ImageNet-1k



But how can we know **when** a new method fails to perform well?

# One role of theory: failure case characterization



## Two examples

### in this talk:

- Failure I: Uncertainty sampling worse than Uniform sampling
- Failure II: Adversarial training worse than Standard training

# Failure I: When uncertainty sampling is worse than uniform sampling

joint work with Alexandru Tifrea, Jacob Clarysse

# Active learning via uncertainty sampling 🤗

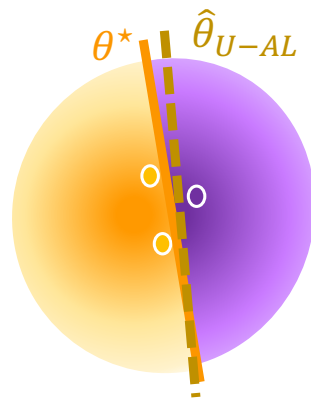
Goal: Find model  $\theta$  with low test error  $\text{Err}(\theta) = \mathbb{E}_{x,y} \ell(y, f_{\theta}(x'))$  using fixed labeling budget  $n_{\ell}$

## Simple and hence often used: Uncertainty based active learning (U-AL)

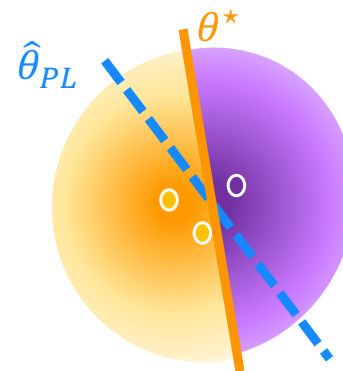
Given uncertainty score, large unlabeled dataset  $D_u$ , labeled seedset  $D_{\ell}$  of size  $n_{seed}$

- At iteration  $t$ :
- Query label  $y^t$  for sample in  $D_u$  with highest uncertainty score for model  $\theta^{t-1}$
  - Remove sample from  $D_u$ , add labeled sample to  $D_{\ell}$ , train  $\theta^t$  on  $D_{\ell}$

uncertainty based  
active learning (U-AL)



better than

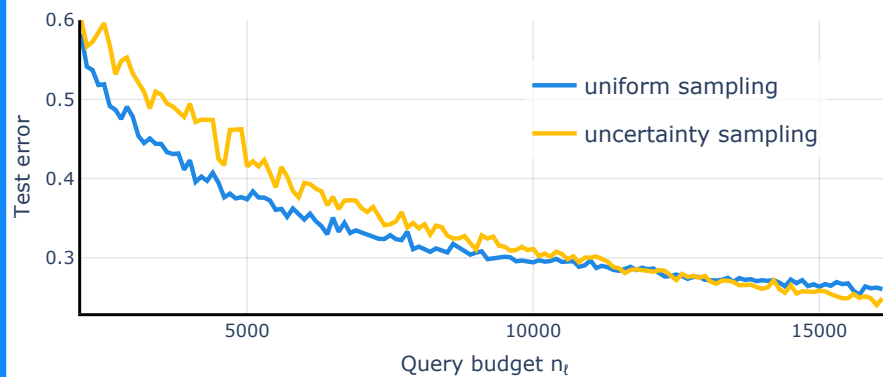


uniform sampling /  
passive learning (PL)

# Failure of uncertainty sampling 🙄

Empirically often reported to fail!

e.g. ResNet18 on CIFAR-100



Theoretically grounded explanations

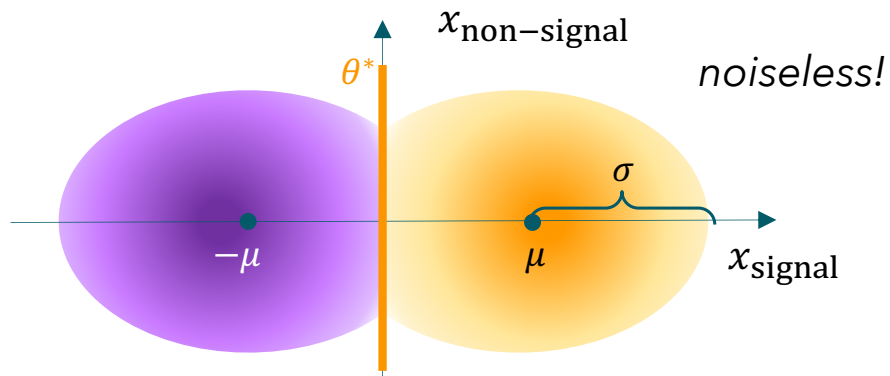
- “cold start” & bad uncertainty estimates  
e.g. [Huang et al. '14], [Sener et al. '18]
- large noise / high Bayes error  
[Mussmann et al. '18]

**Our work:** Different reason why U-AL fails, even with “optimal” uncertainty & noiseless data

# Theoretical results → new failure hypothesis

$n_\ell$  labeled samples from  $d$ -dimensional covariates

- $x_{\text{signal}} \sim$  truncated Gaussian mixture
- $x_{\text{non-signal}} \sim$  isotropic Normal  $N(0, I)$



- $\hat{\theta}$ : linear SVM solution on labeled dataset
- Uncertainty score: distance to decision boundary of current (or optimal) model

**Theorem** [TCY '22] (informal):

For  $n_\ell \ll d$ , large enough unlabeled dataset

$$\text{Err}(\hat{\theta}_{\text{U-AL}}) - \text{Err}(\hat{\theta}_{\text{PL}}) > 0 \text{ w.h.p.}$$

Further, the error gap increases for smaller

- 1  $\frac{n_\ell}{d}$  (query budget)
- 2  $\frac{\mu}{\sigma}$  (class separation).

# Theoretical results → new failure hypothesis

**Empirical hypothesis:** For test accuracy

U-AL may be **worse than** PL even for

noiseless data and oracle uncertainty if

- 1 budget is small
- 2 a lot of unlabeled data near optimal decision boundary



**Theorem** [TCY '22] (informal):

For  $n_\ell \ll d$ , large enough unlabeled dataset

$$\text{Err}(\hat{\theta}_{\text{U-AL}}) - \text{Err}(\hat{\theta}_{\text{PL}}) > 0 \text{ w.h.p.}$$

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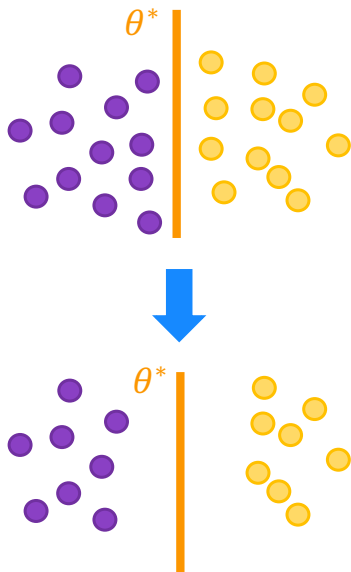
- 1  $\frac{n_\ell}{d}$  (query budget)
- 2  $\frac{\mu}{\sigma}$  (class separation).



# Key property ②: class separation

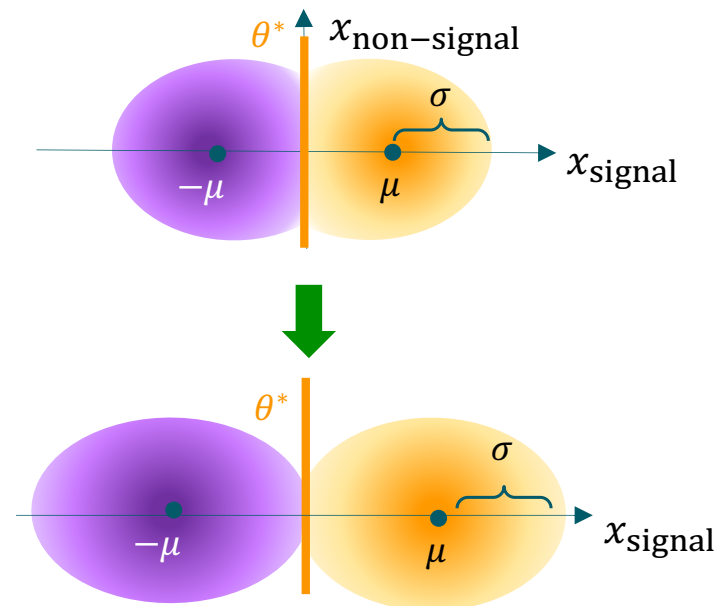
## More class separation on empirical dataset:

Removing % samples closest to decision boundary  $\theta^*$  trained on whole dataset

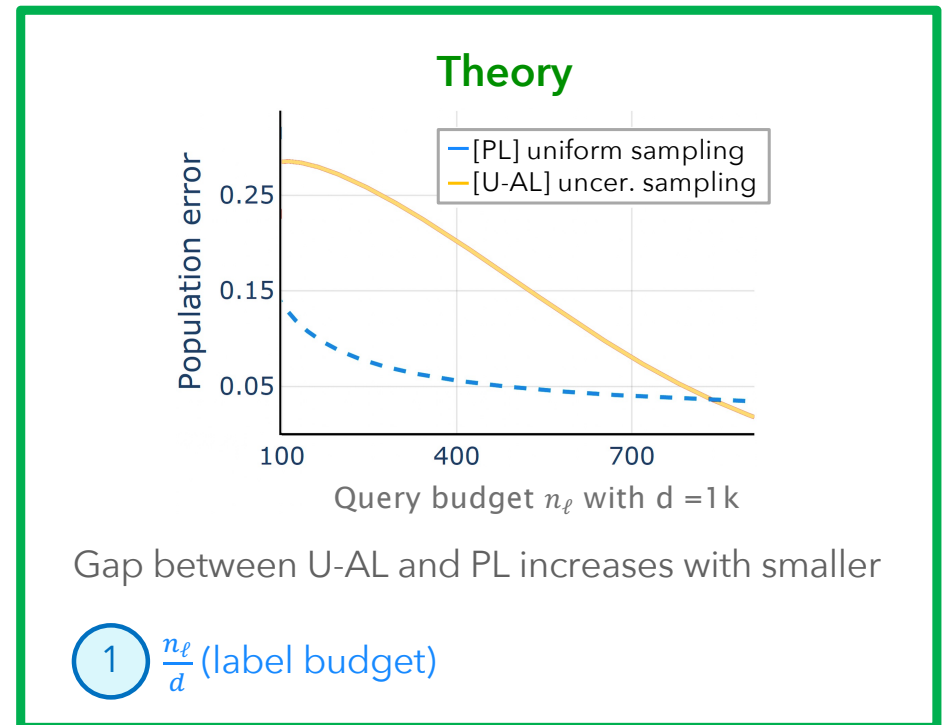
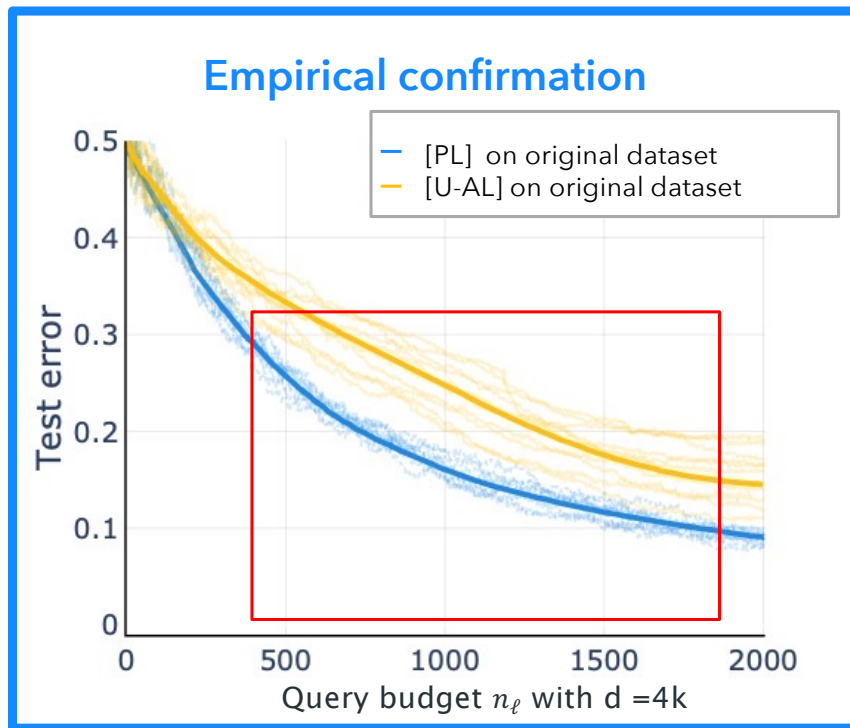


## More class separation in theory

Larger mean separation  $\mu$  in signal direction

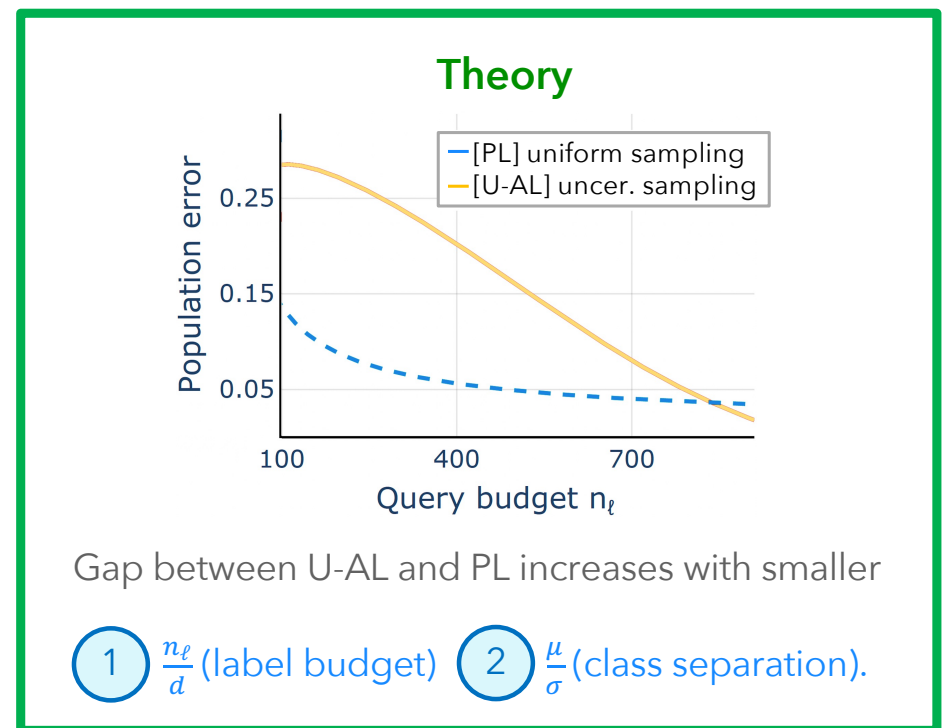
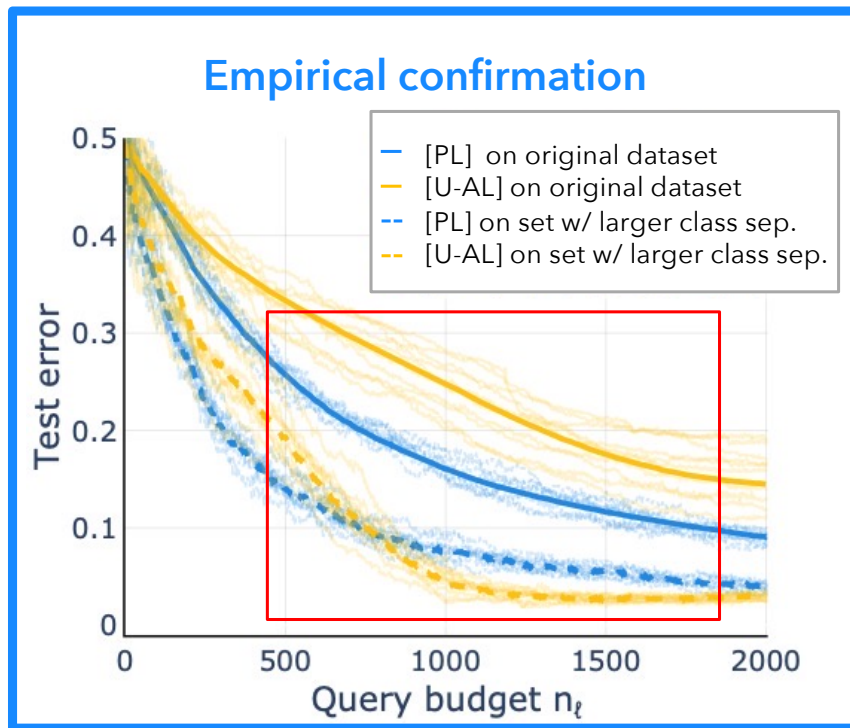


# Empirical validation: ① Failure of small label budget



Happens in a small-sample regime that is still relevant (test accuracy ~ 80%)

# Empirical validation: ② Failure for small separation



Happens in a small-sample regime that is still relevant (test accuracy ~ 80%)

# Failure II: When adversarial training hurts robust generalization

joint work with Jacob Clarysse, Julia Hörrmann

# Adversarial robustness and adversarial training

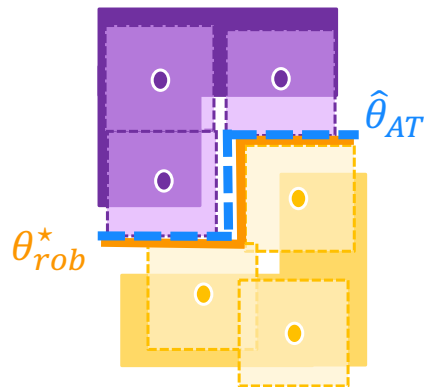


Goal: Low robust error  $\text{RobErr}(\theta) = \mathbb{E}_{x,y} \max_{x' \in T(x,\epsilon)} \ell(y, f(x'; \theta))$  w/  $T(x, \epsilon)$ : set of  $\epsilon$ -perturbed versions of  $x$

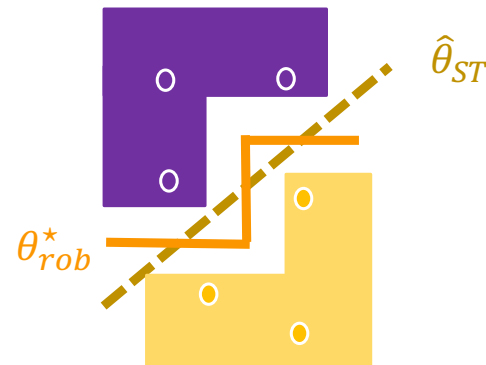
## Adversarial training (AT)

- At iteration  $t$ :
  - for each  $x_i$  in mini-batch, find adversarial example  $x'_i = \arg\max_{x \in T(x_i, \epsilon)} \ell(y_i, f(x; \theta^t))$
  - SGD step on loss w.r.t.  $\theta^t$  at adversarial points  $x'_i$

adversarial training (AT)

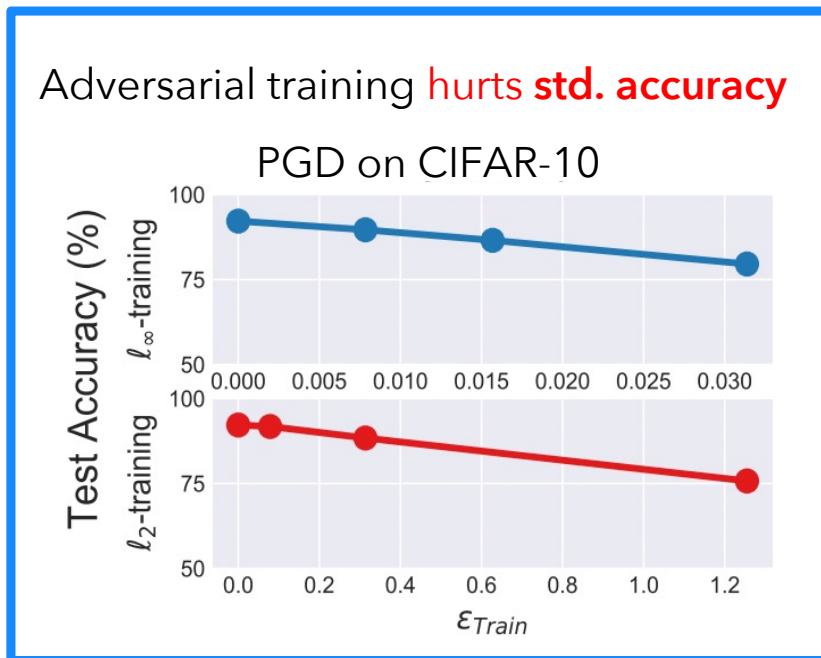


better than



standard training (ST)

# But: Known caveat of adversarial training (AT) 🙄



## Theoretically grounded explanations:

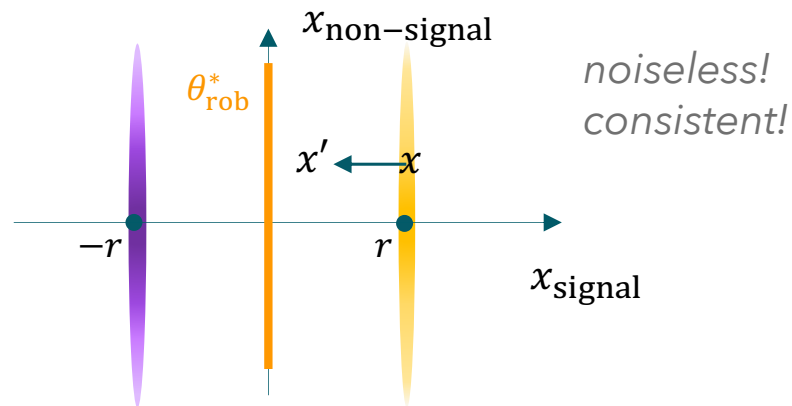
- optimal classifiers not robust (inherent tradeoff), e.g. [Tsipras et al. '19, Zhang et al. '19...]
- robust model more complex [Nakkiran et al. '19]
- wrong inductive bias [Raghunathan et al. '20]

**Our work:** AT may have worse **adv. robust accuracy** even w/o inherent tradeoff in well-specified setting

# Theoretical results → new failure hypothesis

$n$  samples from  $d$ -dimensional covariates

- $x_{\text{signal}} = r \cdot y \theta^*$  for  $y \sim U(\{-1, +1\})$   
 $x_{\text{non-signal}} \sim \text{isotropic Normal } N(0, I)$



- Perturbation set:  $T(x; \epsilon) = \{x + \delta \theta^* \text{ with } |\delta| \leq \epsilon\}$
- $\hat{\theta}$ : GD until convergence on (robust) logistic loss

**Theorem** [CHY '22] (informal):

For  $n < d$ , almost surely

$$\text{RobErr}(\hat{\theta}_{\text{AT}}) - \text{RobErr}(\hat{\theta}_{\text{ST}}) > 0$$

Further, the error gap increases for

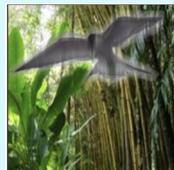
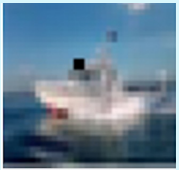
- 1 smaller  $\frac{n}{d}$  (sample size)
- 2 if attack always reduces signal

# Theoretical results → new failure hypothesis

**Empirical hypothesis:** For robust accuracy

AT may be **worse than** ST

- 1 budget is small
- 2 attacks directed to object, such as masks, illumination, motion blur



**Theorem** [CHY '22] (informal):

For  $n < d$ , almost surely

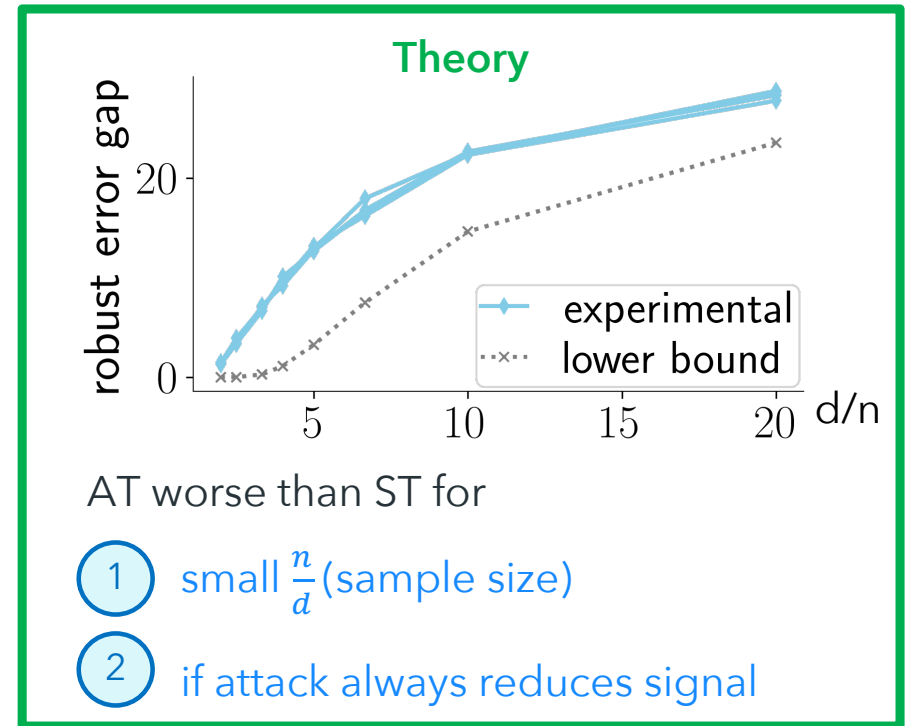
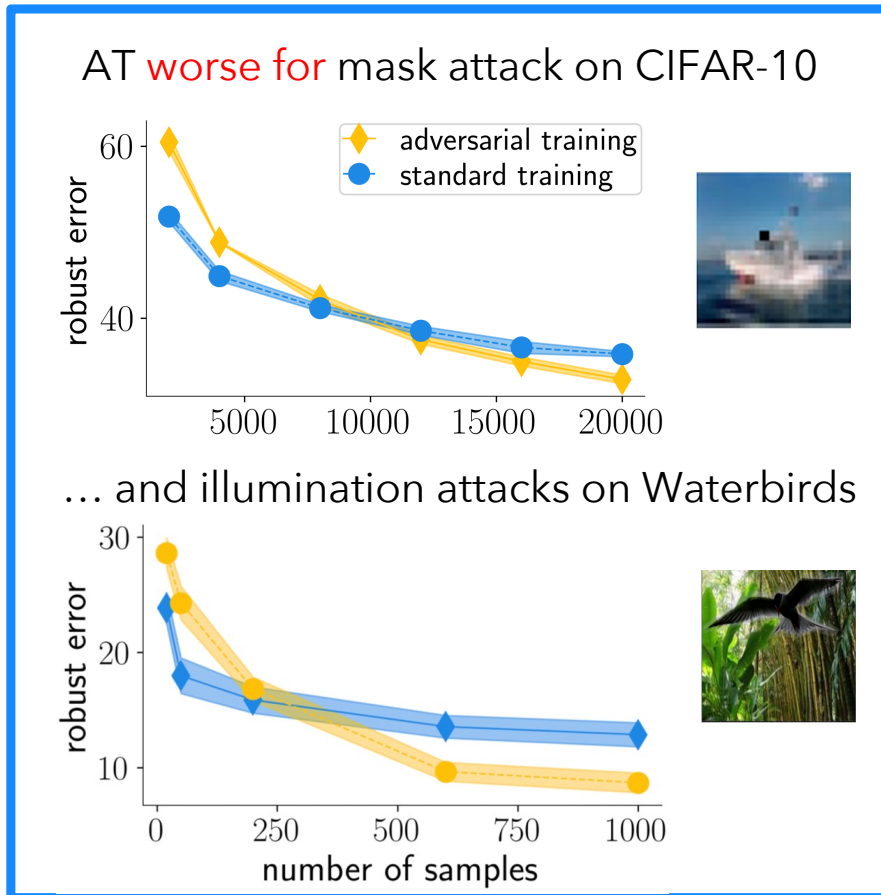
$$\text{RobErr}(\hat{\theta}_{\text{AT}}) - \text{RobErr}(\hat{\theta}_{\text{ST}}) > 0$$

Further, the error gap increases for

- 1 smaller  $\frac{n}{d}$  (sample size)
- 2 if attack always reduces signal



# Empirical validation: Failure for small sample directed attacks

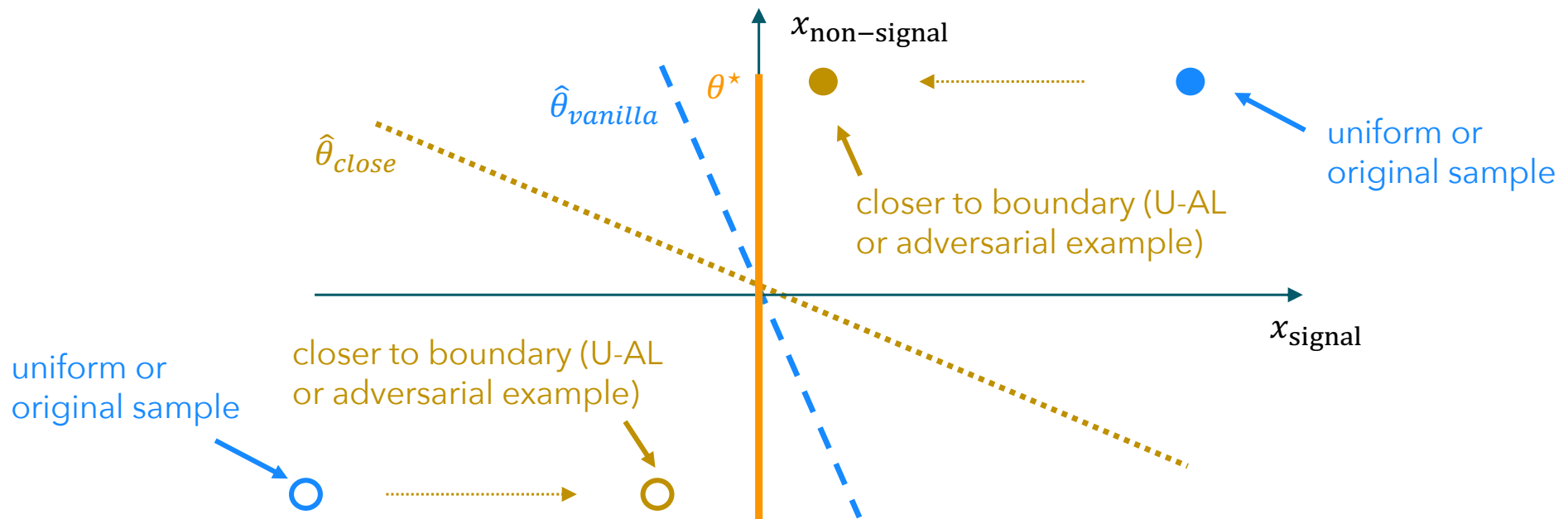


Happens in a small-sample regime that is still relevant (standard accuracy ~ 80%)

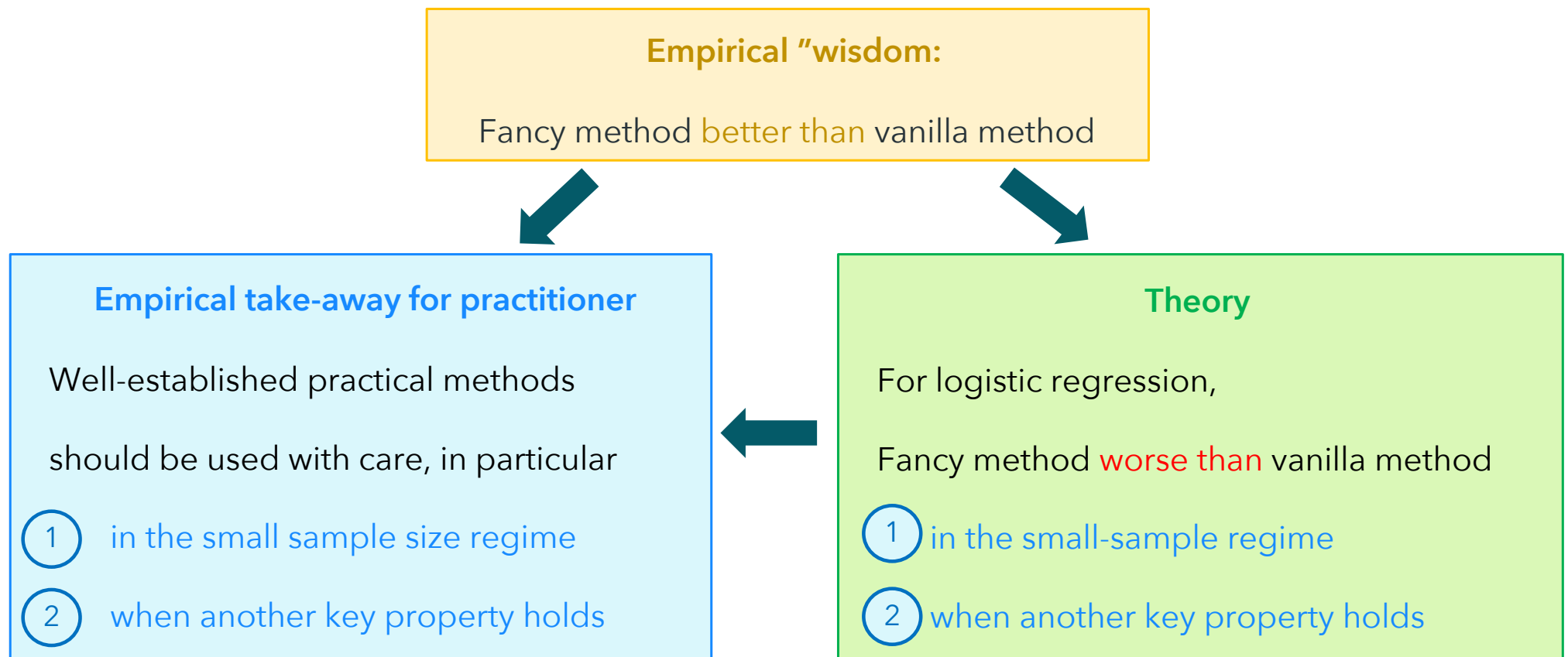
# Common proof intuition for both failure cases

What do AT and (oracle) U-AL have in common?

⇒ Models trained on points closer to good dec. boundary ( $\hat{\theta}_{close}$ )



# Summary: Theory-guided failure case hypotheses



# References, also to more failure cases in modern ML



 SML group: [sml.inf.ethz.ch](https://sml.inf.ethz.ch)

Thanks!  


Papers discussed in this talk

- Clarysse, Hörmann, Yang “**Why adversarial training can hurt robust accuracy**”, arxiv preprint ‘22
- Tifrea, Clarysse, Yang “**Uncertainty vs. uniform sampling: When being passive is better than being active**”, arxiv preprint ‘22

Further “failures” identified in our group:

- Bartolomeis, Clarysse, Yang, Sanyal “**Certified defenses hurt generalization**”, this workshop
- Sanyal\*, Hu\*, Yang “**How unfair is private learning?**”, UAI 2022
- Aerni\*, Milanta\*, Donhauser, Yang “**Strong inductive biases provably prevent harmless interpolation**”, on OpenReview