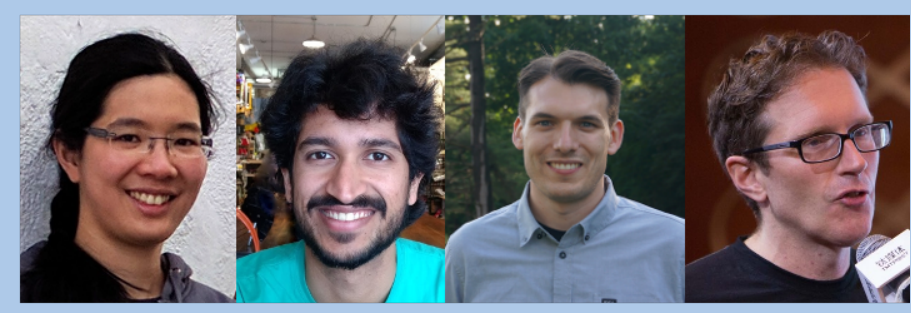




A framework for Multi-(A)rmed/(B)andit Testing with online FDR control

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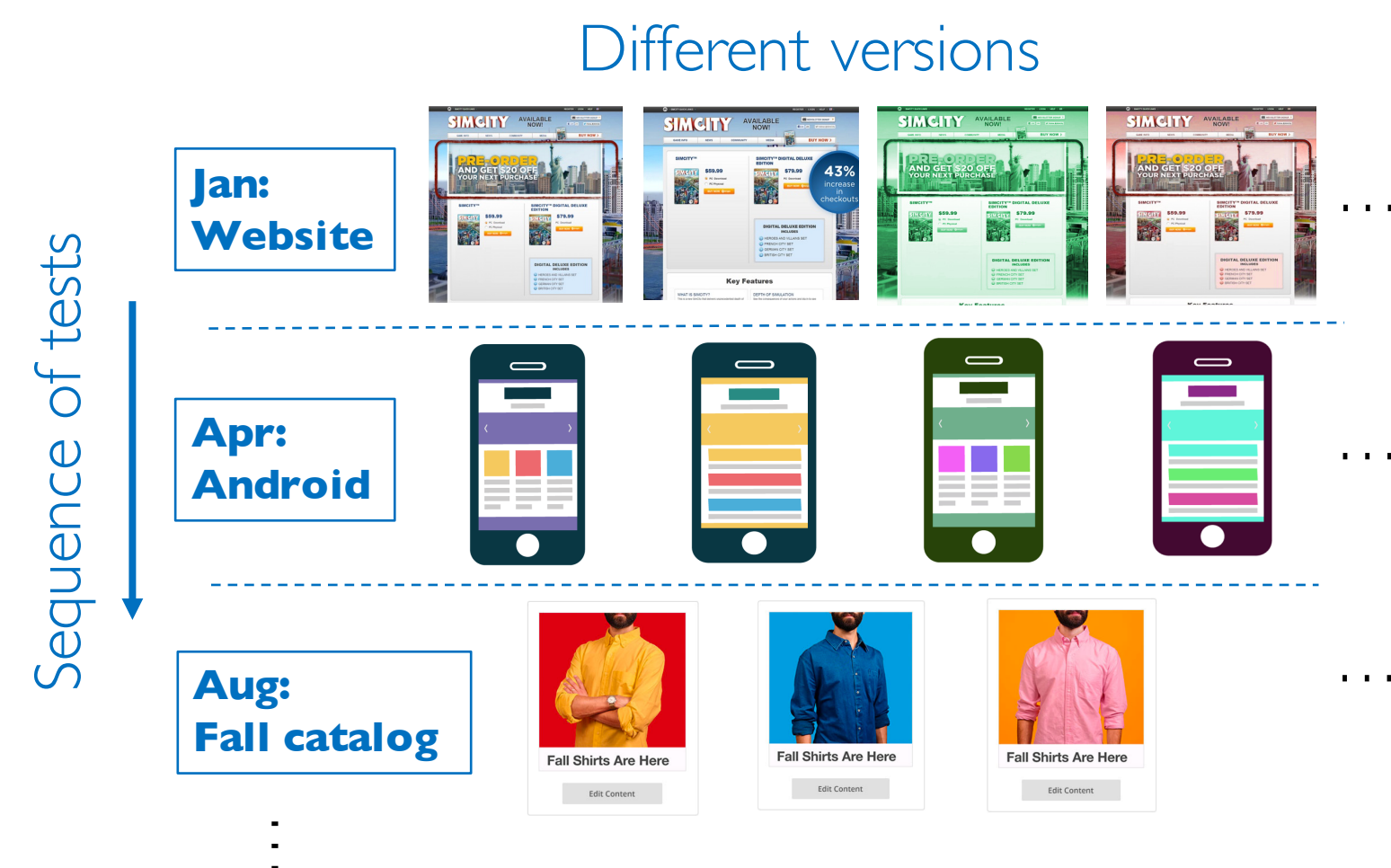


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What we solve

Problem setting:

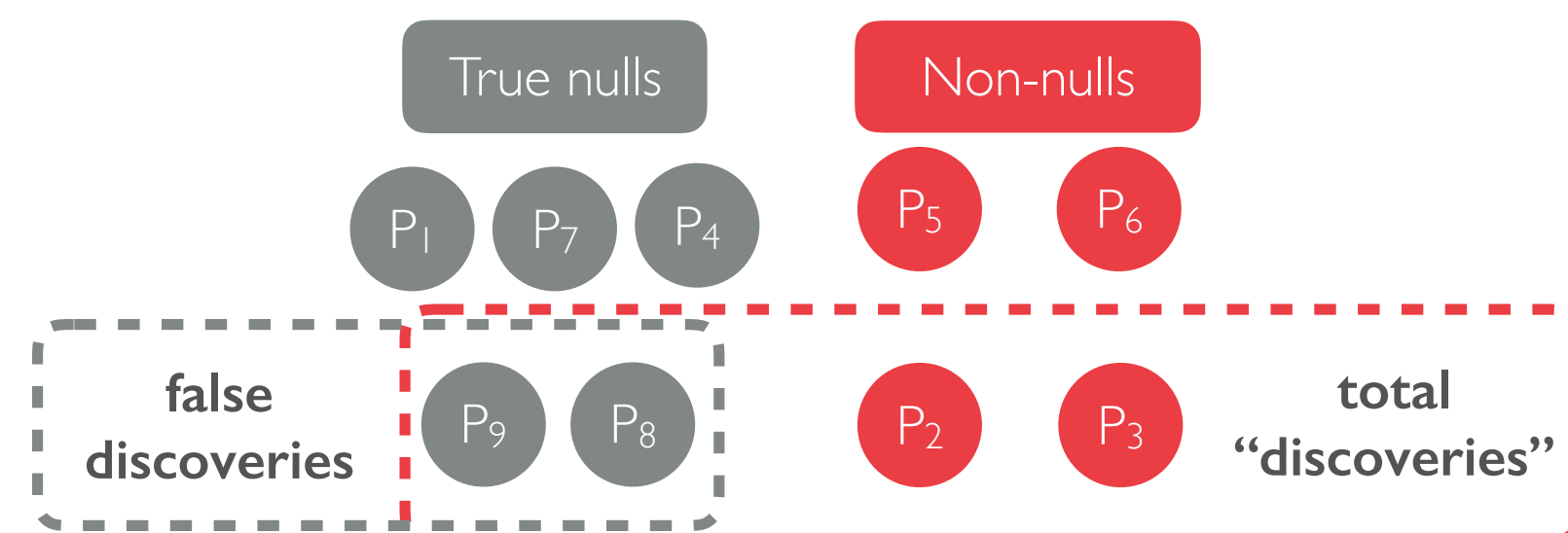
Multiple experiments (*tests*) are conducted sequentially with goal to detect whether one of new versions (*arms*) is better than default by repeatedly getting feedback (*samples*)



Our three high-level goals:

- “False alarms”: Not make too many wrong detections across all tests
→ Control **false discovery rate (FDR) at every test J** (online)

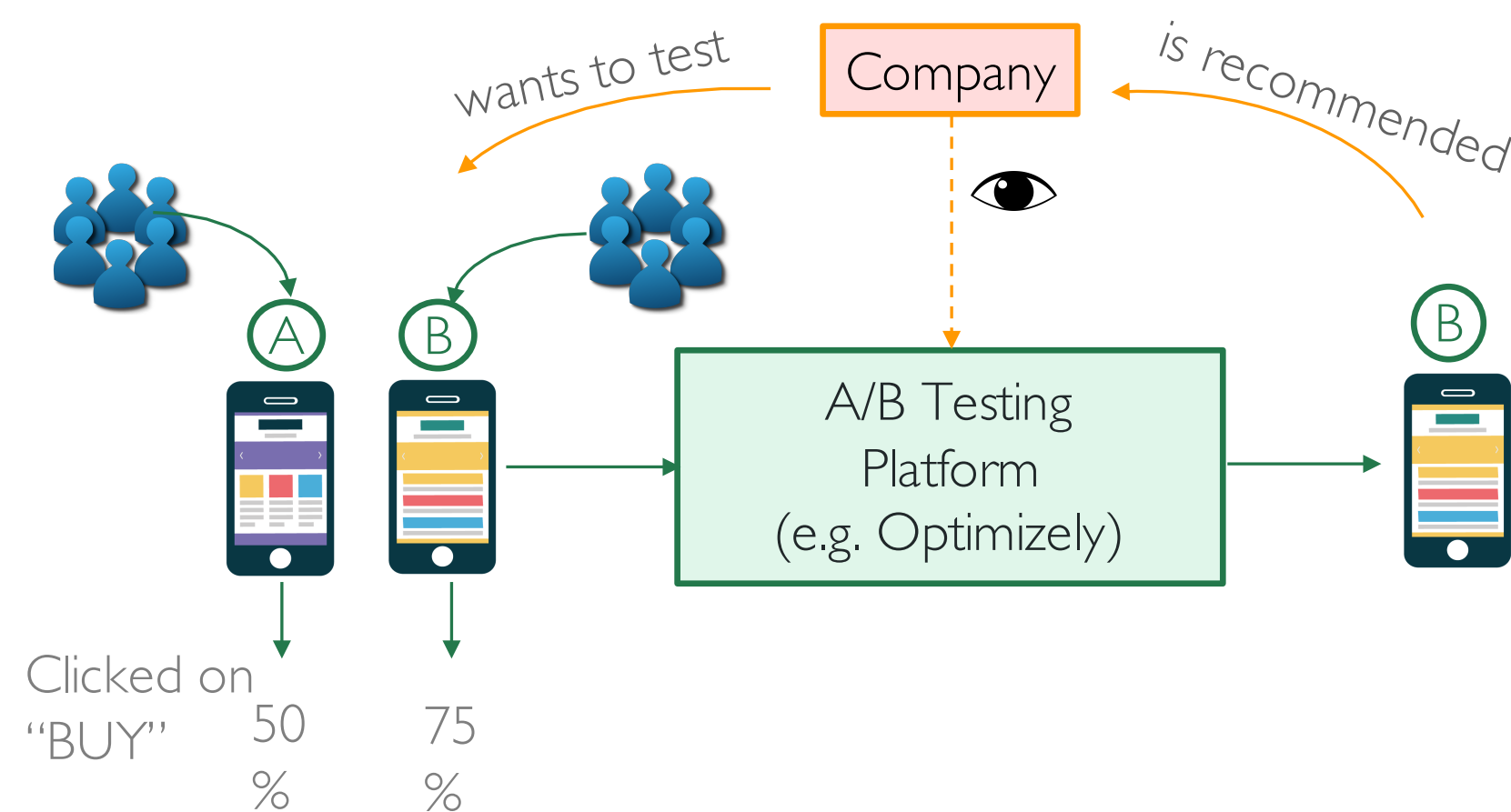
$$FDR(J) = \mathbb{E} \frac{\# \text{ false discoveries}}{\# \text{ total discoveries}}$$



- “Power”: If default is not best, **find best arm**, with at least confidence $1 - \delta$ **using few samples**
- p*-value peeking: Allow for **continuous monitoring** of *p*-value

Status quo: A/B testing

One test, two arms: A user is assigned to each arm with prob. 0.5 (uniform sampling); adjusted *p*-value allows continuous monitoring



Hypothesis testing model where *A* is default (*control*):

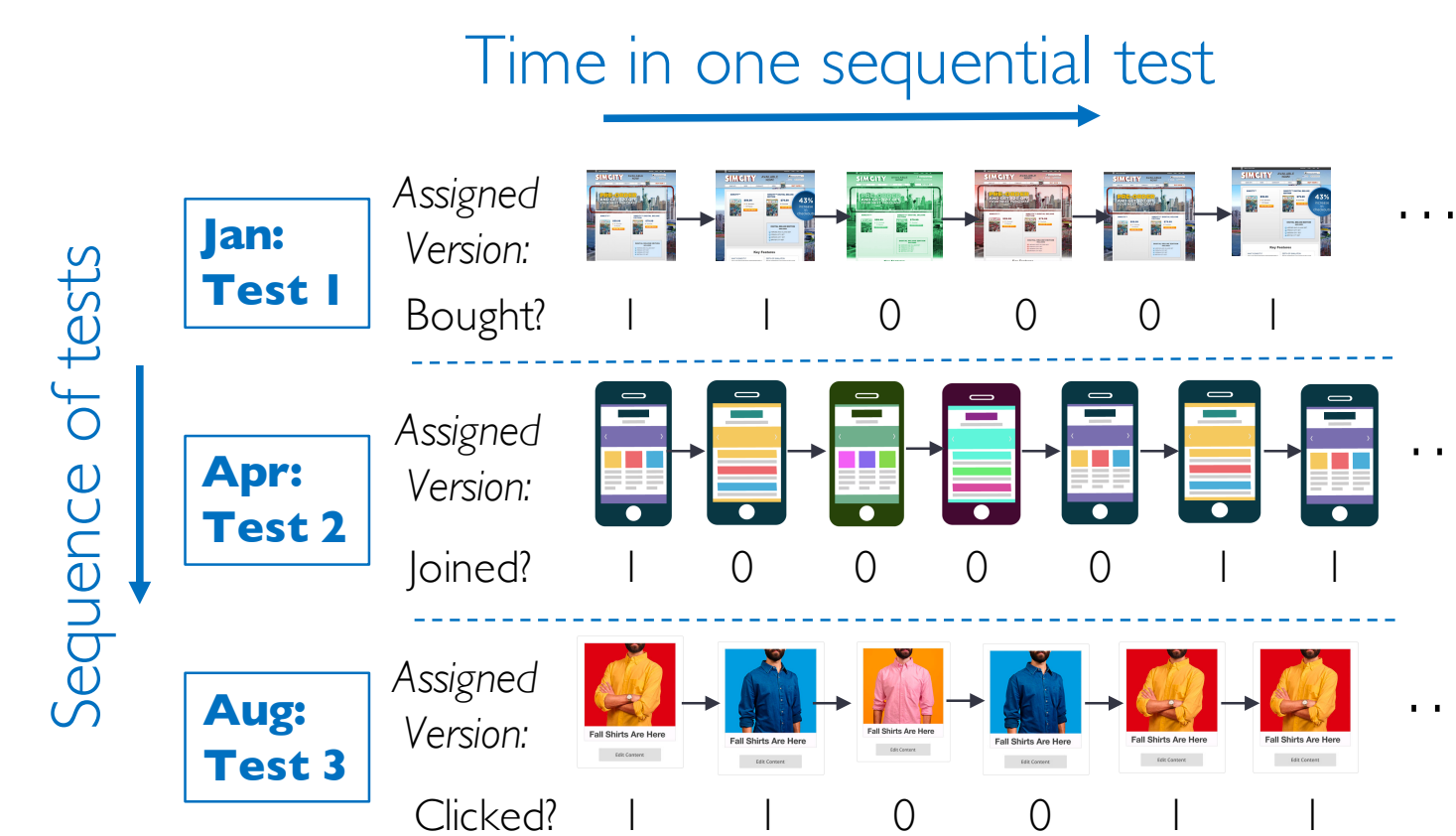
- Samples drawn from distributions $\mathbb{P}_A, \mathbb{P}_B$ with means μ_A, μ_B
- Null hypothesis is $H_0 : \mu_A > \mu_B$, alternative: $H_1 : \mu_A < \mu_B$
- Compute *p*-value, i.e. how extreme a test statistic *T* is
- Null is rejected, $R = 1$, if $p < \alpha$ (significance level)

Major shortcomings of conventional A/B testing

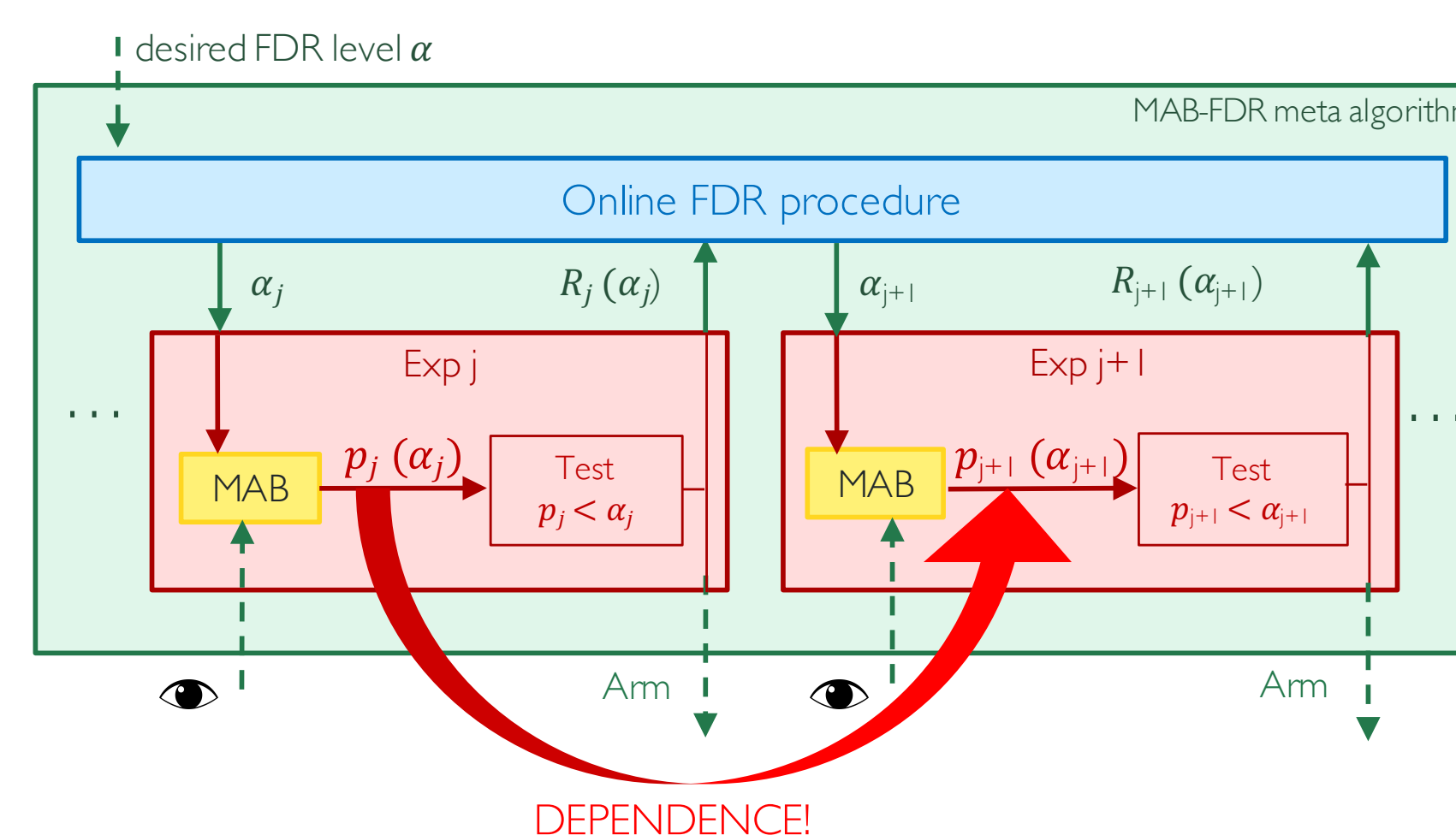
- For K arms, uniform sampling requires $O(K)$ number of samples
- Does not incorporate correction for multiple tests over time

Our approach: doubly-sequential framework

- Use best-arm MAB algorithm for one test → doubly-sequential



- Simultaneously control FDR and sample complexity by interaction between best-arm MAB and FDR



- How is α_j used in best-arm MAB to have low sample complexity?
- How do we obtain “always valid *p*-values” from MAB exp.?
- p*-values are now dependent, FDR still controlled?

Contrib. I: MAB-FDR procedure for multiple tests

Algorithm 1 MAB-FDR

```

for  $j = 1, 2, \dots$  do
  Test  $j$  receives one control and  $K(j)$  alternatives
   $\alpha_j = \text{ONLINEFDR}(\{P_{\ell}^{j-1}\}_{\ell=1}^j)$ 
   $(i_b, P_T^j) = \text{BEST-ARM MAB}_j(\alpha_j)$ 
  if  $i_b$  is not the control and  $P_T^j \leq \alpha_j$  then
    reject the null hypothesis of test  $j$ ; return  $i_b$  to user
  Return  $P_T^j$  to ONLINEFDR
  
```

with T either MAB stopping time or user-defined truncation time.

Theorem:

- $FDR(J) \leq \alpha$ and $BDR(J) \geq \frac{\sum_{j \in \mathcal{H}_1(J)} (1 - \alpha_j)}{|\mathcal{H}_1(J)|}$
- For each experiment i , MAB only draws as many samples as are needed to guarantee online FDR control at level α and power.

Contrib. II: Testing vs. MAB perspective for one test

Setting: K arms, i_* actual best arm, i_b bandit arm

- What's the null hypothesis? For FDR (“false alarms”) control, we only care if **control is actually best**, i.e.

$$H_0 : \mu_0 > \mu_i \quad \forall i = 1, \dots, K \quad \text{vs.} \quad H_1 : \exists i \text{ s.t. } \mu_0 < \mu_i$$

- What about power? Best-arm MAB goal: find **best arm**

$$BDR = \frac{\mathbb{E} \sum_{j \in \mathcal{H}_1} R_j \mathbb{I}_{\mu_{i_b} = \mu_{i_*}}}{|\mathcal{H}_1(J)|}$$

Insight: Best-arm MAB is capable of both testing for null hypothesis adaptively **and** finding best arm

Key quantity: Always valid *p*-values using best-arm MAB

- Main tool: Non-asymptotic Law of Iterated Logarithm (LIL)
→ always valid confidence interval:

$$\mathbb{P}(\exists t : \mu_{i,t} \notin [\text{LCB}_i(t, \delta), \text{UCB}_i(t, \delta)]) \leq \delta$$

with $\text{UCB}_i(t, \delta), \text{LCB}_i(t, \delta) = \hat{\mu}_i \pm c \sqrt{\frac{\log(\frac{1}{\delta}) + \log \log(n)}{n}}$

- Compute *p*-value using duality w/ confidence intervals & LIL:

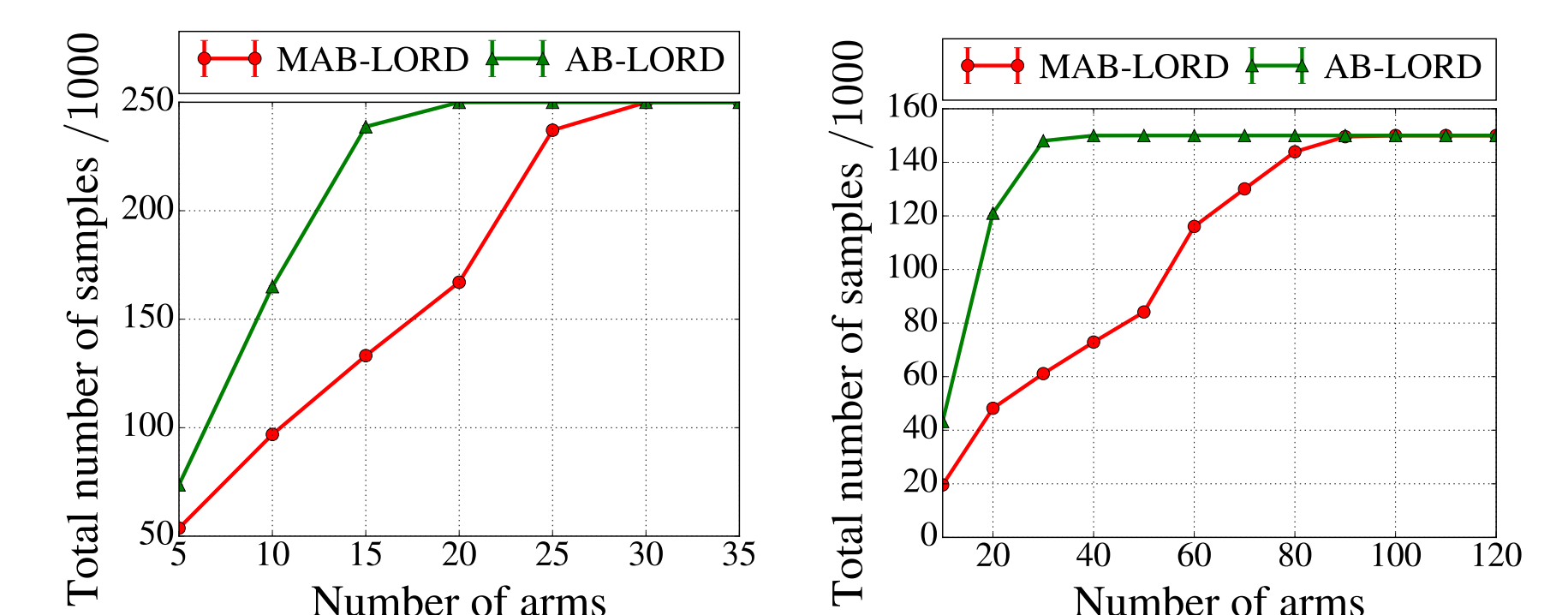
$$P_{i,t} : \sup \left\{ \gamma \in [0, 1] \mid \text{LCB}_i(n_i(t), \gamma) \leq \text{UCB}_0(n_0(t), \gamma) + \epsilon \right\}$$

p-value at each time-step t (within one MAB exp.) is defined as $P_t := \min_{s \leq t} \min_{i=1, \dots, K} P_{i,s}$.

Proposition: p_t is an always valid *p*-value!

Simulations

Sample complexity vs. number of arms per experiment for: Bernoulli (left, 50 hyp.) and Gaussian (right, 500 hyp.) draws



Background: onlineFDR procedure

Key idea: The more rejections up until j , the higher the *wealth* and thus available significance level α_j for next test j

