

### DINFK

## Detecting when the available data does not allow reliable inference

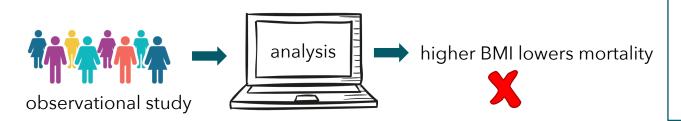
Fanny Yang, Statistical Machine Learning Group
Department of Computer Science @ETH Zurich

joint work with students Alex Tifrea, Eric Stavarache, Piersilvio de Bartolomeis, Javier A. Martinez, Konstantin Donhauser





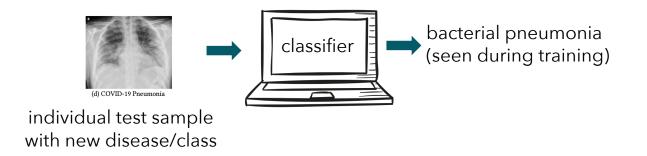




Problem 1
too much hidden
confounding



Problem (1)
too much hidden
confounding



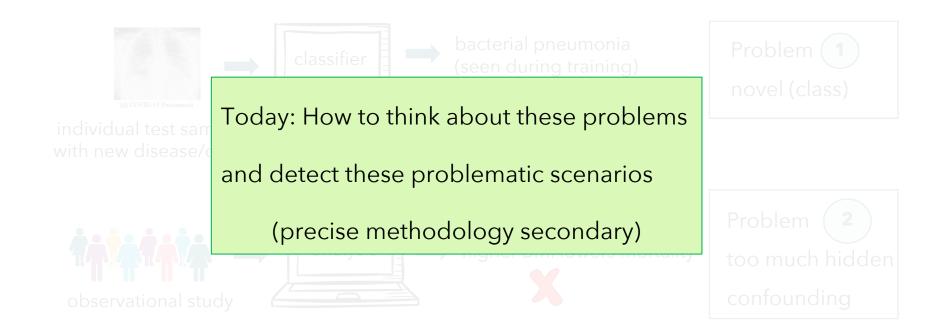
with new disease/class



Problem (1)
too much hidden
confounding



Problem 2 novel (class)





### DINFK

# I. A lower bound for hidden confounding using randomized control trials

joint work with Piersilvio de Bartolomeis, Javier Abad Martinez, Konstantin Donhauser

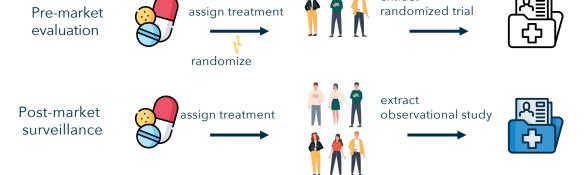
work in progress

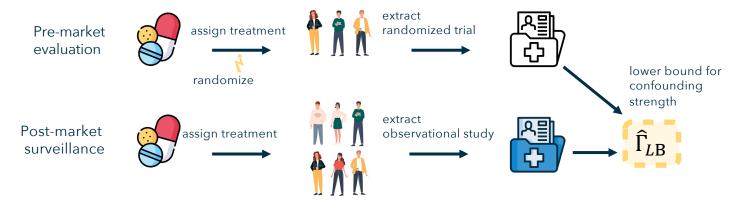


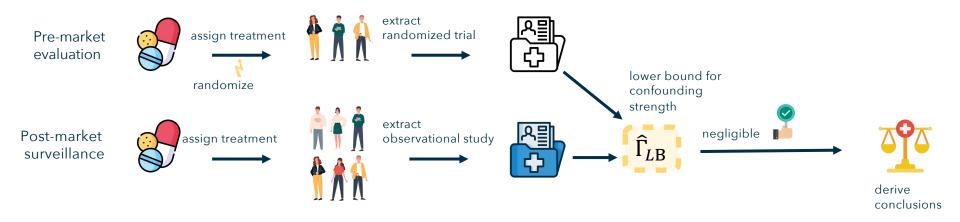


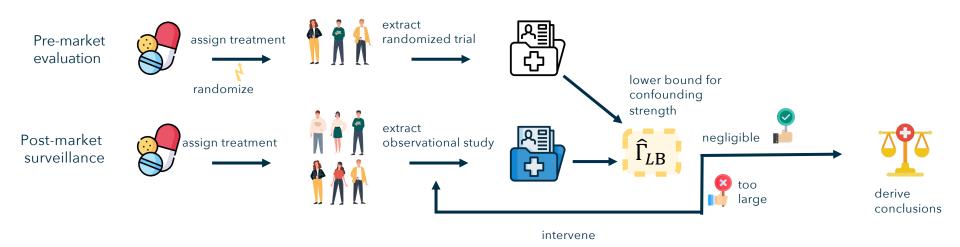


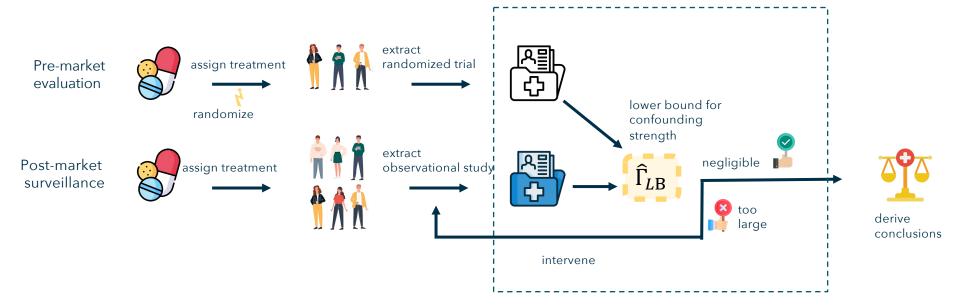










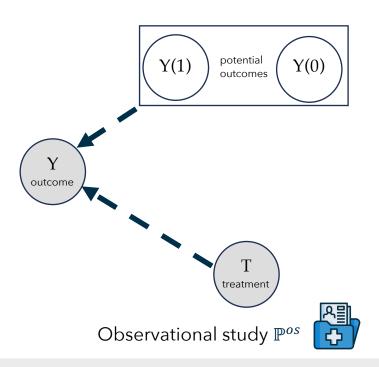


- 1. Scenarios where we can't make inference using the observational study
- 2. Approach: How to detect these scenarios?

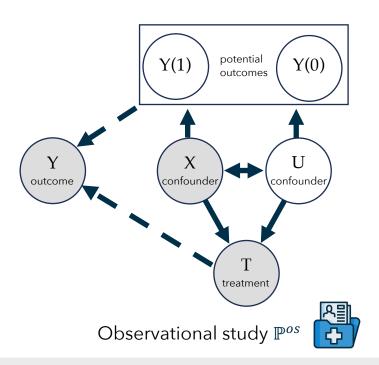
### Potential outcome framework



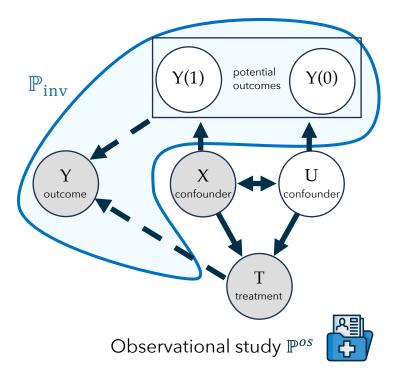
### Potential outcome framework



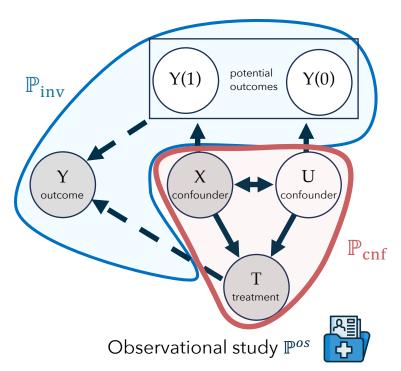
### Potential outcome framework



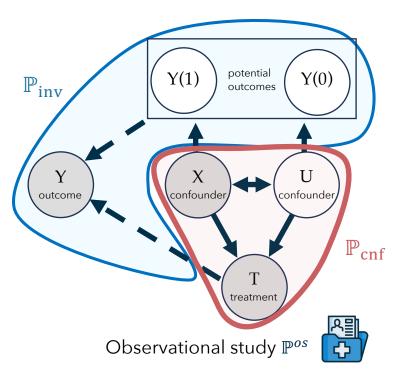
### Potential outcome framework

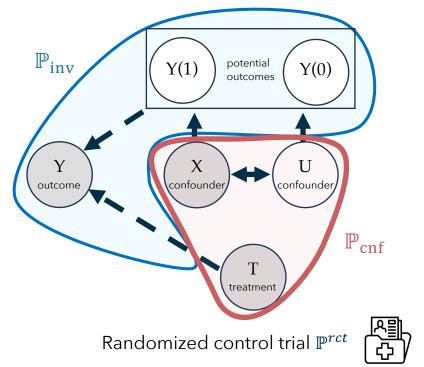


### Potential outcome framework



### Potential outcome framework





#### Additional assumptions:

- Transportability of CATE, i.e.  $\mathbb{E}_{\mathbb{P}^{os}}[Y(1) Y(0) \mid X] = \mathbb{E}_{\mathbb{P}^{rct}}[Y(1) Y(0) \mid X]$
- Support inclusion  $supp(\mathbb{P}^{rct}) \subseteq supp(\mathbb{P}^{os})$

#### Additional assumptions:

- Transportability of CATE, i.e.  $\mathbb{E}_{\mathbb{P}^{os}}[Y(1) Y(0) \mid X] = \mathbb{E}_{\mathbb{P}^{rct}}[Y(1) Y(0) \mid X]$
- Support inclusion  $supp(\mathbb{P}^{rct}) \subseteq supp(\mathbb{P}^{os})$

#### Definitions:

•  $\mathbb{P}^{os}$  satisfies  $\mathsf{MSM}(\Gamma)$  if  $\Gamma^{-1} \leq \frac{\mathbb{P}^{os}(T=1|X,U)}{\mathbb{P}^{os}(T=0|X,U)} / \frac{\mathbb{P}^{os}(T=1|X)}{\mathbb{P}^{os}(T=0|X)} \leq \Gamma$  almost surely (Tan-06)

#### Additional assumptions:

- Transportability of CATE, i.e.  $\mathbb{E}_{\mathbb{P}^{os}}[Y(1) Y(0) \mid X] = \mathbb{E}_{\mathbb{P}^{rct}}[Y(1) Y(0) \mid X]$
- Support inclusion  $supp(\mathbb{P}^{rct}) \subseteq supp(\mathbb{P}^{os})$

#### Definitions:

 $\Gamma = 1 \triangleq unconfoundedness$ 

•  $\mathbb{P}^{os}$  satisfies  $\mathsf{MSM}(\Gamma)$  if  $\Gamma^{-1} \leq \frac{\mathbb{P}^{os}(T=1|X,U)}{\mathbb{P}^{os}(T=0|X,U)} / \frac{\mathbb{P}^{os}(T=1|X)}{\mathbb{P}^{os}(T=0|X)} \leq \Gamma$  almost surely (Tan-06)

#### Additional assumptions:

- Transportability of CATE, i.e.  $\mathbb{E}_{\mathbb{P}^{os}}[Y(1) Y(0) \mid X] = \mathbb{E}_{\mathbb{P}^{rct}}[Y(1) Y(0) \mid X]$
- Support inclusion  $supp(\mathbb{P}^{rct}) \subseteq supp(\mathbb{P}^{os})$

#### Definitions:

 $\Gamma = 1 \triangleq unconfoundedness$ 

- $\mathbb{P}^{os}$  satisfies MSM( $\Gamma$ ) if  $\Gamma^{-1} \leq \frac{\mathbb{P}^{os}(T=1|X,U)}{\mathbb{P}^{os}(T=0|X,U)} / \frac{\mathbb{P}^{os}(T=1|X)}{\mathbb{P}^{os}(T=0|X)} \leq \Gamma$  almost surely (Tan-06)
- true confounding strength  $\Gamma^*(\mathbb{P}^{os})$ : The smallest  $\Gamma$  for which  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma)$

#### Additional assumptions:

- Transportability of CATE, i.e.  $\mathbb{E}_{\mathbb{P}^{os}}[Y(1) Y(0) \mid X] = \mathbb{E}_{\mathbb{P}^{rct}}[Y(1) Y(0) \mid X]$
- Support inclusion  $supp(\mathbb{P}^{rct}) \subseteq supp(\mathbb{P}^{os})$

#### Definitions:

 $\Gamma = 1 \triangleq unconfoundedness$ 

- $\mathbb{P}^{os}$  satisfies MSM( $\Gamma$ ) if  $\Gamma^{-1} \leq \frac{\mathbb{P}^{os}(T=1|X,U)}{\mathbb{P}^{os}(T=0|X,U)} / \frac{\mathbb{P}^{os}(T=1|X)}{\mathbb{P}^{os}(T=0|X)} \leq \Gamma$  almost surely (Tan-06)
- true confounding strength  $\Gamma^*(\mathbb{P}^{os})$ : The smallest  $\Gamma$  for which  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma)$

Scenarios we want to detect: when true confounding  $\Gamma^*$  of  $\mathbb{P}^{os}$  is too large

- 1. Scenarios where we can't make inference using the observational study
- 2. Approach: How to detect these scenarios?

#### Our plug-and-play approach for desired significance $\alpha$ :

1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$ 

27

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma: \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\rm thresh}$

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma : \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

$$\text{ATE sensitivity bounds } \mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \ \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma : \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

ATE sensitivity bounds 
$$\mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \quad \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$
 all full distributions that yield observed  $\mathbb{P}_{X,Y,T}^{os}$  and satisfy MSM( $\Gamma$ )

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma: \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

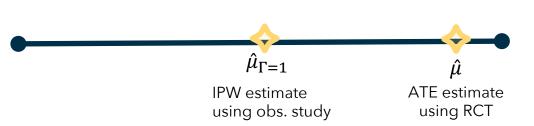
$$\text{ATE sensitivity bounds } \mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \ \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$



#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma : \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

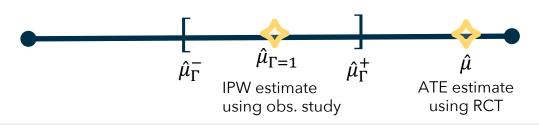
$$\text{ATE sensitivity bounds } \mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \ \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$



#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma : \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

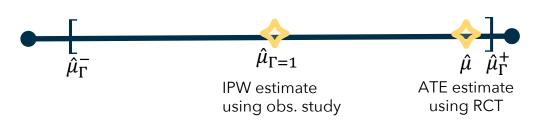
$$\text{ATE sensitivity bounds } \mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \ \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$



#### Our plug-and-play approach for desired significance $\alpha$ :

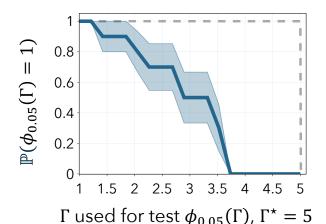
- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma : \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\text{thresh}}$
- Test  $H_0(\Gamma) \iff$  test whether  $\mu \in [\mu_{\Gamma}^-, \mu_{\Gamma}^+]$  with ATE  $\mu = \mathbb{E}_{\mathbb{P}}[Y(1) Y(0)]$  and

$$\text{ATE sensitivity bounds } \mu_{\Gamma}^- = \inf_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)], \ \mu_{\Gamma}^+ = \sup_{\widetilde{\mathbb{P}} \in P_{\Gamma}(\mathbb{P}_{X,Y,T}^{os})} \mathbb{E}_{\widetilde{\mathbb{P}}}[Y(1) - Y(0)]$$



#### Our plug-and-play approach for desired significance $\alpha$ :

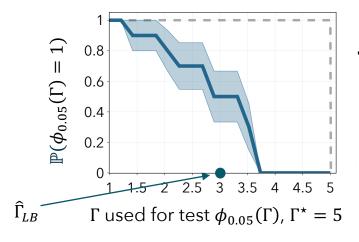
- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB}=\inf\left\{\Gamma\colon\phi_{lpha}(\Gamma)=0\right\}$  and flag if  $\hat{\Gamma}_{LB}>\Gamma_{
  m thresh}$



probability of rejection over 20 runs on semi-synthetic data

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB}=\inf\left\{\Gamma\colon\phi_{lpha}(\Gamma)=0\right\}$  and flag if  $\hat{\Gamma}_{LB}>\Gamma_{
  m thresh}$

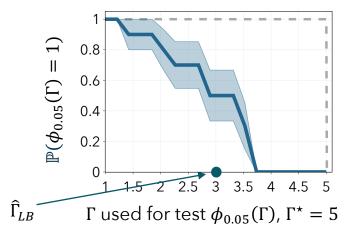


probability of rejection over 20 runs on semi-synthetic data

# Our paradigm: finding a lower bound

#### Our plug-and-play approach for desired significance $\alpha$ :

- 1. Test  $\phi_{\alpha}(\Gamma)$  of the null  $H_0(\Gamma)$ :  $\mathbb{P}^{os}$  satisfies  $MSM(\Gamma) \iff \Gamma^* \leq \Gamma$
- 2. Report  $\hat{\Gamma}_{LB} = \inf \{ \Gamma: \phi_{\alpha}(\Gamma) = 0 \}$  and flag if  $\hat{\Gamma}_{LB} > \Gamma_{\rm thresh}$



- probability of rejection over 20 runs on semi-synthetic data
  - asymptotically  $\mathbb{P}(\hat{\Gamma}_{LB} > \Gamma^*) \leq \alpha$ implied by  $\mathbb{P}(\phi_a(\Gamma^*) = 1) \leq \alpha$

- without RCT and using sensitivity bounds
  - $\circ$  quantification via critical value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vanderWeele-Ding-17, Jin-Ren-Candes-23 etc.

- without RCT and using sensitivity bounds
  - $\circ$  quantification via critical value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vanderWeele-Ding-17, Jin-Ren-Candes-23 etc.

but: can be arbitrarily far from  $\Gamma^*$ 

- without RCT and using sensitivity bounds
  - $\circ$  quantification via critical value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vanderWeele-Ding-17, Jin-Ren-Candes-23 etc.

but: can be arbitrarily far from  $\Gamma^*$ 

 $_{\circ}$  can test joint null hypothesis ATE(obs. study) > 0 and MSM( $\Gamma$ ) holds e.g. Yadlowsky-Namkoong-Basu-Duchi-Tian-22, Jin-Ren-Candes-23

- without RCT and using sensitivity bounds
  - o quantification via critical value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vanderWeele-Ding-17, Jin-Ren-Candes-23 etc.
    - but: can be arbitrarily far from  $\Gamma^*$
  - $\circ$  can test joint null hypothesis ATE(obs. study) > 0 and MSM( $\Gamma$ ) holds e.g. Yadlowsky-Namkoong-Basu-Duchi-Tian-22, Jin-Ren-Candes-23
    - but: rejection only means either  $MSM(\Gamma)$  assumption wrong or ATE  $\leq 0$

- without RCT and using sensitivity bounds
  - o quantification via critical value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vanderWeele-Ding-17, Jin-Ren-Candes-23 etc.

but: can be arbitrarily far from  $\Gamma^*$ 

can test joint null hypothesis ATE(obs. study) > 0 and MSM(Γ) holds
 e.g. Yadlowsky-Namkoong-Basu-Duchi-Tian-22, Jin-Ren-Candes-23
 but: rejection only means either MSM(Γ) assumption wrong or ATE ≤ 0

#### • with RCT:

 $_{\circ}$  binary test for existence of confounding with H  $_{0}\colon \Gamma^{\star}>1$  e.g. Viele et al '14, Hussein-Oberst-Shih-Sontag '22

## Previous paradigms that can be used for detection

#### without RCT and using sensitivity bounds

o quantification via critical gamma value  $\hat{\Gamma}_{ct}$  that changes causal conclusions e.g. vander but: can out  $\Gamma^*$  true statement about  $\Gamma^*$  not possible! TE(obs. study) > 0 and our paradigm: statement about  $\Gamma^*$  but: rejection only means either MSM( $\Gamma$ ) assumption & flag only if  $\Gamma^*$  large

#### with RCT:

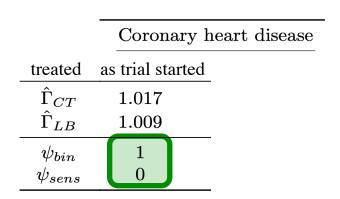
• binary te e.g. Viele e half  $\Gamma^*$  small solution founding with  $H_0\colon \Gamma^*>1$  Sontag '22

- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease

- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment



- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment





- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment

	Coronary heart disease			
treated	as trial started	before trial		
$\hat{\Gamma}_{CT}$	1.017	1.164		
$\hat{\Gamma}_{LB}$	1.009	1.224		
$\overline{\psi_{bin}}$	1	1		
$\psi_{sens}$	0	1		



- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment



	Coronary heart disease			
treated	as trial started	d before trial		
$\hat{\Gamma}_{CT}$	1.017	1.164		
$\hat{\Gamma}_{LB}$	1.009	1.224		
$\overline{\psi_{bin}}$	1	1		
$\psi_{sens}$	0	1		

Different paradigms for "flagging" confounding:

Compute  $\hat{\Gamma}_{CT}$  that changes ATE sign and compare let "expert" assess "likeliness"

- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment



	Coronary heart disease			
treated	as trial started		before trial	
$\hat{\Gamma}_{CT}$	1.017		1.164	
$\hat{\Gamma}_{LB}$	1.009		1.224	
$\overline{\psi_{bin}}$	1		1	
$\psi_{sens}$	0		1	

Different paradigms for "flagging" confounding:

- Compute  $\hat{\Gamma}_{CT}$  that changes ATE sign and compare let "expert" assess "likeliness"
- $\psi_{bin}$ : tests for existence, e.g. check  $\hat{\Gamma}_{LB} > 1$

- Randomized trial and observational study (1993-2005)
- Treatment: hormone replacement therapy
- Outcomes: coronary heart disease
- hidden confounder (revealed later): start of treatment



	Coronary heart disease				
treated	as trial sta	rted	before trial		
$\hat{\Gamma}_{CT}$	1.017		1.164		
$\hat{\Gamma}_{LB}$	1.009		1.224		
$\overline{\psi_{bin}}$	1		1		
$\psi_{sens}$	0		1		

Different paradigms for "flagging" confounding:

- Compute  $\hat{\Gamma}_{CT}$  that changes ATE sign and compare let "expert" assess "likeliness"
- $\psi_{bin}$ : tests for existence, e.g. check  $\hat{\Gamma}_{LB} > 1$
- $\psi_{sens}$  (ours): check whether too large  $\widehat{\Gamma}_{LB} > \widehat{\Gamma}_{CT}$

#### Current and future work

#### Higher power using

- kernelized test as opposed to averaging
- non-"adversarial" sensitivity model

#### Extended applicability:

- multiple observational studies (no RCT)
- Automatic detection of hidden confounders from set of features



### **D**INFK

II. Semi-supervised novelty detection using ensembles with regularized disagreement

joint work with Alexandru Tifrea, Eric Stavarache

published at UAI '22

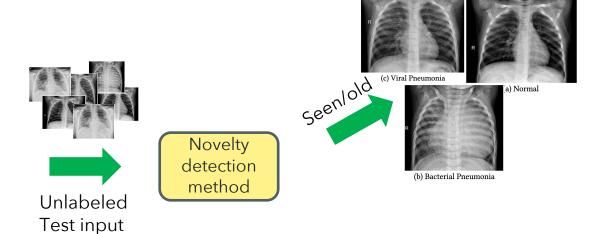




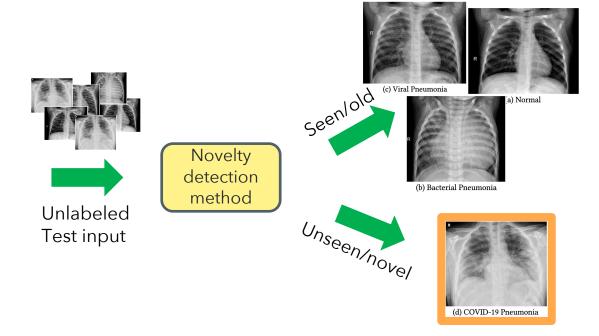




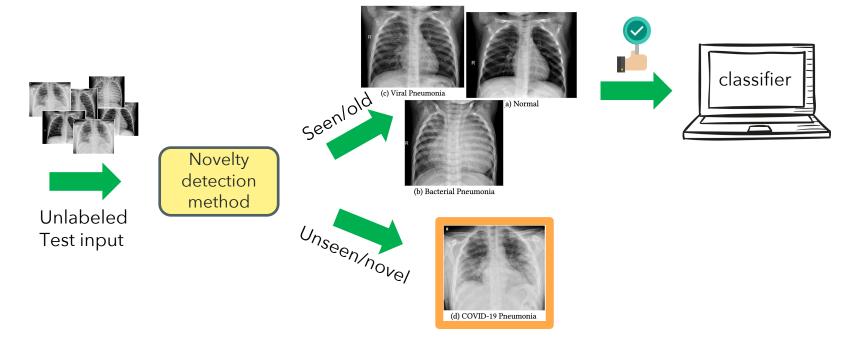
Unlabeled Test input Novelty detection method



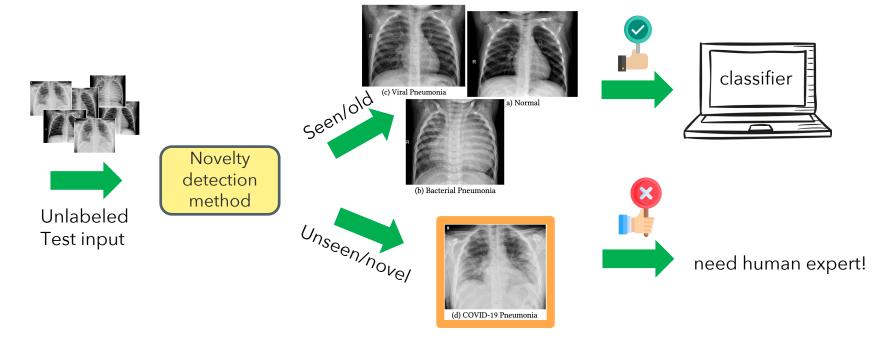
Novelty detection method tells user that software doesn't "know enough" to predict new point



Novelty detection method tells user that software doesn't "know enough" to predict new point



Novelty detection method tells user that software doesn't "know enough" to predict new point



- 1. Definition: Points we can't make inference on
- 2. Approach: How to detect those samples?

#### What's "novel" to a trained model?

"novel" / o.o.d. points: test points  $x \in X$  the model cannot reliably predict.

#### What's "novel" to a trained model?

"novel" / o.o.d. points: test points  $x \in X$  the model cannot reliably predict.

First: which points  $x \in X$  can a model predict "reliably" in an unseen test set?

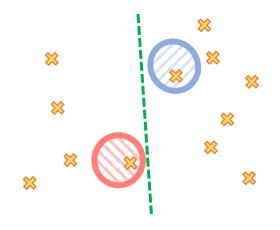
· i.d. generalization from finite samples (traditional learning theory) and

#### What's "novel" to a trained model?

"novel" / o.o.d. points: test points  $x \in X$  the model cannot reliably predict.

First: which points  $x \in X$  can a model predict "reliably" in an unseen test set?

- i.d. generalization from finite samples (traditional learning theory) and
- o.o.d. generalization (extrapolatable from training distribution) depends on test shift & model complexity



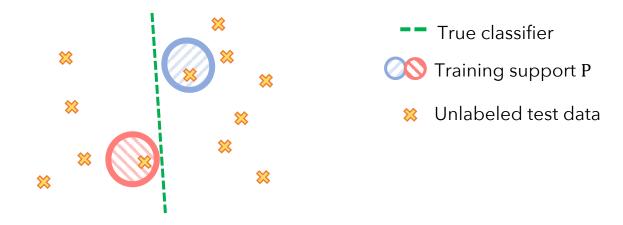




Unlabeled test data

Extrapolatable given training distribution + linear ground truth:

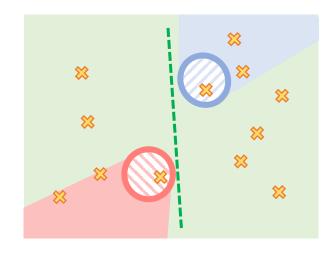
Points  $x \in X$  where the set of all linear Bayes optimal classifiers agree on



Extrapolatable given training distribution + linear ground truth:

Points  $x \in X$  where the set of all linear Bayes optimal classifiers agree on

intersecting all optimal classifiers yields



- True classifier

  Training support P

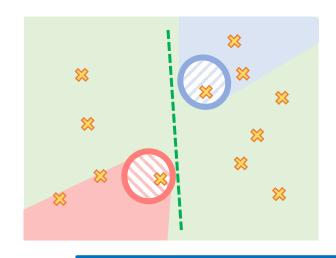
  Unlabeled test data

  Correctly extrapolatable
- Not extrapolatable (OOD)

Extrapolatable given training distribution + linear ground truth:

Points  $x \in X$  where the set of all linear Bayes optimal classifiers agree on

intersecting all optimal classifiers yields



True classifier

\infty Training support P

💢 Unlabeled test data

Correctly extrapolatable

Not extrapolatable (OOD)

Goal now: how to output green area

- 1. Definition: Points we can't make inference on
- 2. Approach: How to detect those samples?

OOD definition suggests following procedure: given K models

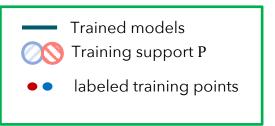
- with good validation accuracy on old classes
- but different predictions outside of training distribution

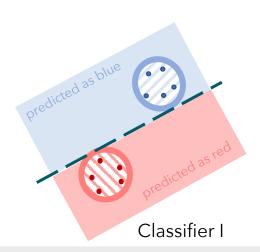
OOD definition suggests following procedure: given K models

- with good validation accuracy on old classes
- but different predictions outside of training distribution
- → flag all points where the models disagree as "novel"

OOD definition suggests following procedure: given K models

- with good validation accuracy on old classes
- but different predictions outside of training distribution
- → flag all points where the models disagree as "novel"



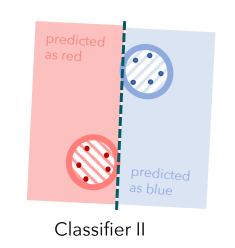


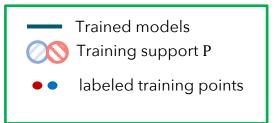
OOD definition suggests following procedure: given K models

with good validation accuracy on old classes

Classifier I

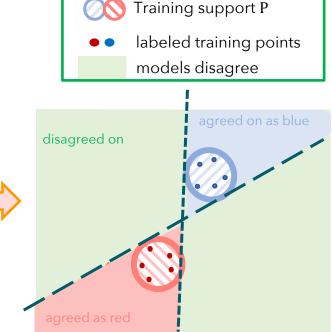
- but different predictions outside of training distribution
- → flag all points where the models disagree as "novel"



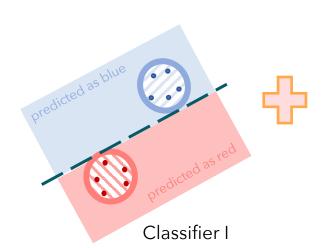


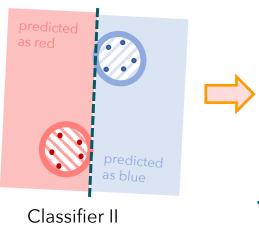
OOD definition suggests following procedure: given K models

- with good validation accuracy on old classes
- but different predictions outside of training distribution
- → flag all points where the models disagree as "novel"



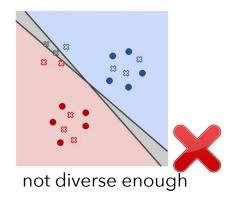
Trained models



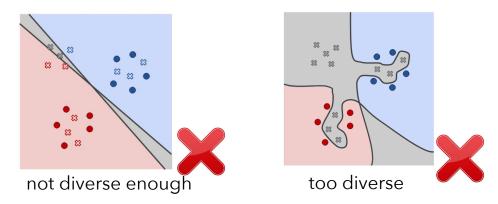


# Key for our improvement: Regularized disagreement

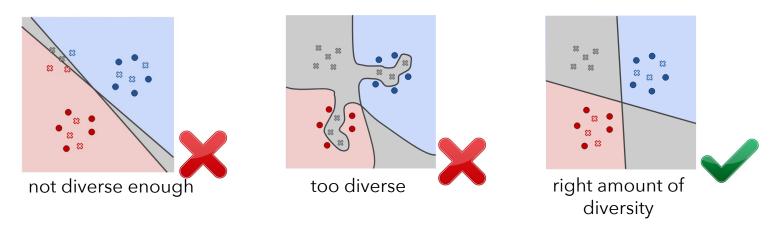
Key for "good performance": Complexity of ensemble models being only as large as needed



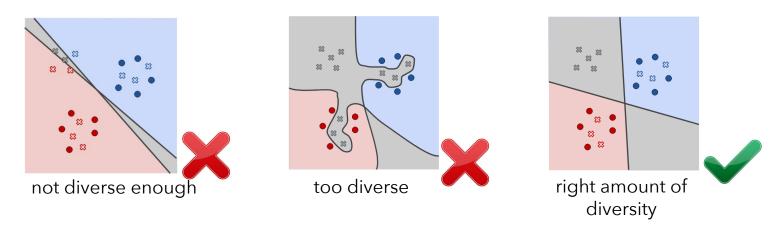
Key for "good performance": Complexity of ensemble models being only as large as needed



Key for "good performance": Complexity of ensemble models being only as large as needed

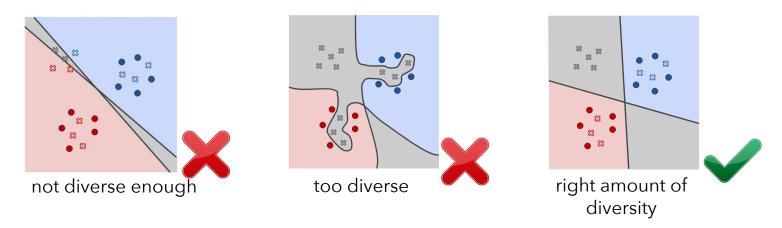


Key for "good performance": Complexity of ensemble models being only as large as needed



Idea for right amount of disagreement: maximize disagreement s.t. validation error of all models small "regularization"

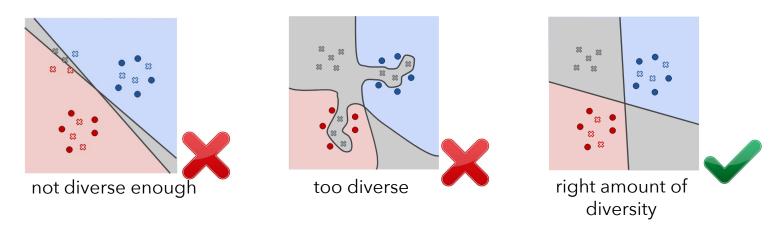
Key for "good performance": Complexity of ensemble models being only as large as needed



Idea for right amount of disagreement: maximize disagreement s.t. validation error of all models small "regularization"

using unlabeled test data

Key for "good performance": Complexity of ensemble models being only as large as needed



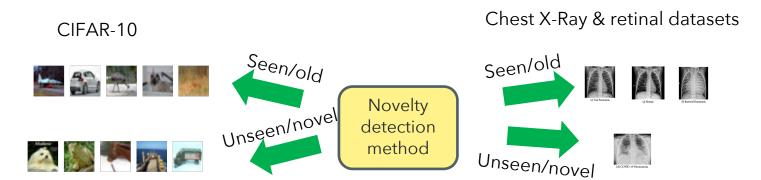
Idea for right amount of disagreement: maximize disagreement s.t. validation error of all models small

"regularization"

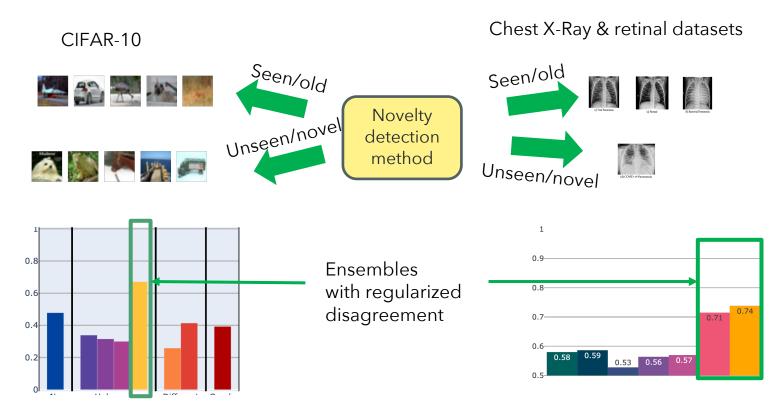
using unlabeled test data

using labeled training data

#### The near OOD problem on images with DNN



#### The near OOD problem on images with DNN



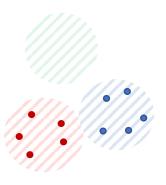




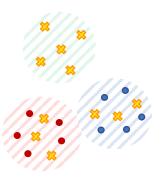


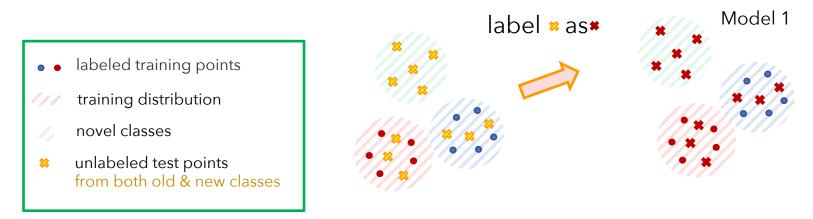
- "Hidden yet quantifiable: A lower bound for confounding strength using randomized trials" by Piersilvio De Bartolomeis\*, Javier Abad\*, Konstantin Donhauser, FY, arxiv preprint
- "Semi-supervised novelty detection using ensembles with regularized disagreement" by Alexandru Ţifrea, Eric Stavarache, and FY, (UAI), 2022

- labeled training points
- training distribution
  - novel classes
- unlabeled test points from both old & new classes

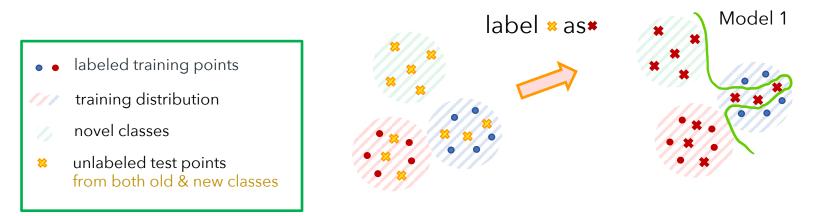


- labeled training points
- training distribution
- novel classes
- unlabeled test points from both old & new classes



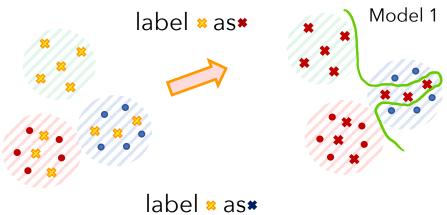


Artificially label all unlabeled test data with one label

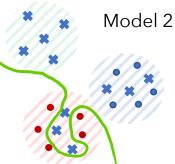


Artificially label all unlabeled test data with one label

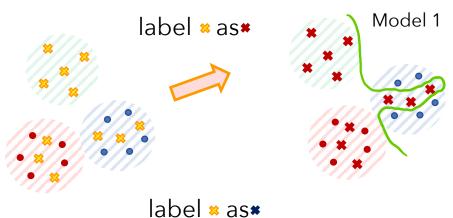
- • labeled training points
- training distribution
  - novel classes
- unlabeled test points from both old & new classes



- Artificially label all unlabeled test data with one label
- Fit different models on labeled & (differently) artificially labeled points

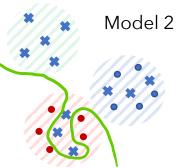


- labeled training points
- training distribution
  - novel classes
- unlabeled test points from both old & new classes

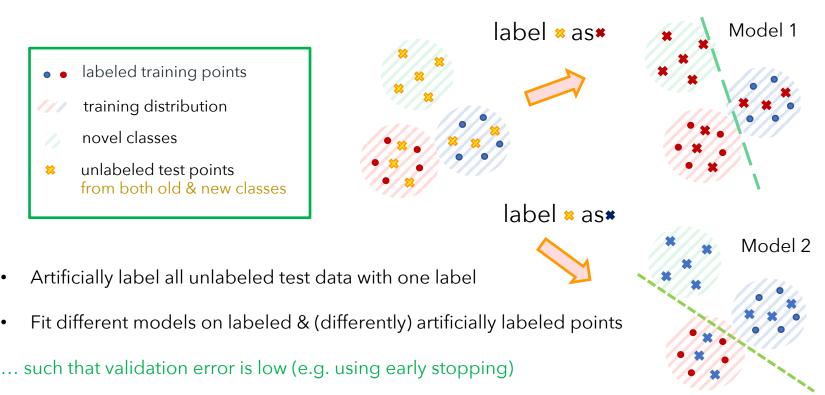


- Artificially label all unlabeled test data with one label
- Fit different models on labeled & (differently) artificially labeled points

... NNs can fit every point perfectly → disagree on all test points

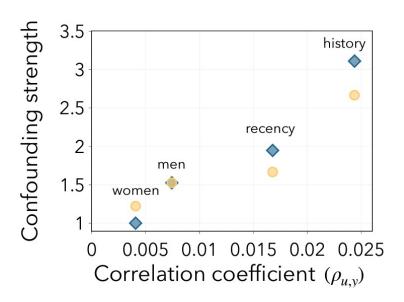


#### Regularizing disagreement using labeled data



#### Current and future work

#### Non-adversarial confounding



#### Discussion of the paradigm

- Propose two tests  $\phi(\Gamma)$  based on (C)ATE sensitivity analysis intervals
  - obs: estimate mu with importance weighting rct, then ATE sensitivity
     valid when ATE bounds are asymptotically normal
  - $_{\circ}$  rct: estimate mu on rct, then CATE sensitivity on obs -> average on rct valid when CATE sensitivity bounds converge at a  $1/\sqrt{n}$  rate and  $n_{rct} \ll n_{os}$